

Product Catalog Automation

Solutions for Automation, Diagnostics and Connectivity

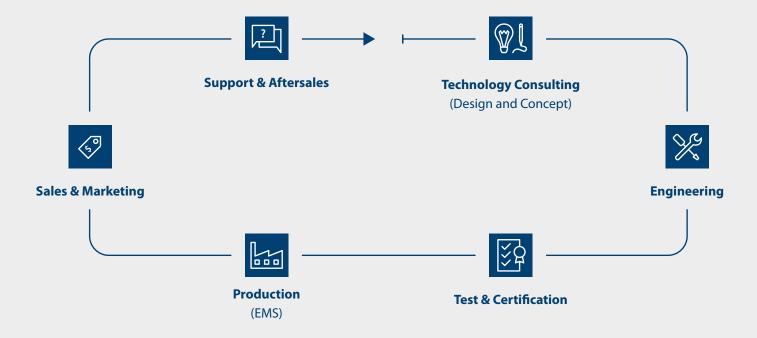












Sontheim – your system supplier for innovative electronics

As a specialist for fieldbus-based communication, control and diagnostic tasks, we are at your side as a reliable partner with our in-depth system know-how. Our modular hardware and software solutions enable optimal networking, automation and analysis of your automotive and industrial systems.

We cover the entire product life cycle, from the design and development phase through production to integration and support. The range of services includes individual prototypes, series deliveries up to customized solutions and complete technology, on-site consulting and training.

Our system solutions







Diagnostics







Connectivity

Our services

For 25 years, our customers worldwide have received a wide range of hardware and software components as well as automation and diagnostic technology services. Sontheim represents technically outstanding products, very close customer service and the combination of individual components to a complete solution that suits your needs. We offer both standardized and customer-specific products tailored to your individual requirements.

We apply our know-how in the area of fieldbus technology in various branches of the automation and automotive industry and thus cover a wide range of applications. Our focus is especially on CAN, EtherCAT, PROFIBUS and the protocols in the automotive sector. We support our customers worldwide, from the first idea and development phase to integration, support and beyond.



Technology Consulting – We bring your ideas to series

From the very beginning, we support you in your tasks and draw on our years of experience from many successfully implemented projects. Through our active participation in various standardization committees such as ASAM, CiA or the AEF, we have the most up-to-date knowledge of the latest standards and technologies. This expertise is always incorporated into our consulting services and guarantees state-of-the-art developments for our customers.

Engineering – As a system provider, we realize your ideas

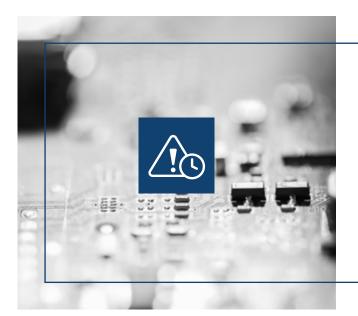
As an expert in various fieldbus technologies, we support you with customer-specific developments. This covers the areas of software, hardware, firmware as well as design and conception of your automation or automotive solution. Current topics such as efficient energy management, the optimal use of resources or solutions for Industry 4.0, drive us to develop innovative products and integrate them into your system.



Custom electronic systems and components

On our modern production lines we manufacture electronic components and systems according to your ideas in best quality, on schedule and of course cost-optimized. We are characterized by our flexibility and can assemble and manufacture batch sizes from just one prototype to series orders of almost 1,250,000 units per year. Our certifications confirm our constant focus on quality.





Obsolescence Management

With the help of our obsolescence management, we check and monitor the entire life cycle of your product. Often, semiconductors in particular have a shorter life cycle than the entire product and thus the production capability of electronic components depends to a large extent on these components. Our customers receive all relevant information over the complete product life cycle in order to be able to react at an early stage.

Workshops and Trainings

Are you looking for suitable training on CAN, current diagnostic applications and standards such as ODX and OTX, or detailed workshops on our products and services? We would be happy to impart the necessary knowledge in a workshop at our premises or at your site. Here we design the training courses individually and adapted to your needs and convey the contents in an understandable and user-oriented way.





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We automate and digitize industrial plants and machines and enable applications for Industry 4.0. Our system solutions enable OEMs to configure, parameterize and control their fieldbus network and to operate an effective analysis and evaluation of the machine status. We have many years of know-how in the field of industrial communication and offer solutions for CAN, CANopen, EtherCAT, Ethernet, PROFIBUS, PROFINET and other fieldbuses.

Benefit from integrated solutions for the automation of your plants. In the field of process automation, we have control solutions, such as industrial PCs, embedded PCs up to programmable logic controllers (PLC) with CODESYS and robust terminal and panel PC solutions. Extremely high-performance IO modules allow a tailor-made design for the most diverse fieldbus networks. Close and flexible data communication ensures an efficient and future-proof system.

Industrial Automation

Controls, IO Modules, Computer-on-Modules, Drive Technologie, Printing Technologie







eControl micro II

Compact and powerful PLC with scalable CPU and high-resolution 7" touch display. IoT-ready and flexible use due to a high number of powerful and standardized interfaces.

Key Features



OPC UA



CODESYS V3.5 acc. to IEC 61131-3



EtherCAT acc. to IEC 61131-3



CAN acc. to ISO 11898



7" TFT display with capacitive touch



WLAN optional



Bluetooth optional



CE certified

At a glance

Equipped with an OPC UA server the use for IoT applications is possible independent of manufacturer, platform and fieldbus, making the controller universally usable. The PLC has a scalable CPU that has been specially optimized for CODESYS target and web visualizations. A capacitive touch display makes operation user-friendly through high accuracy and multi-touch capability. A variety of interfaces – such as Ethernet, Bluetooth, WLAN, USB, CAN, EtherCAT and digital In- and Outputs – complete the package.

Benefits

- Compact, powerful and scalable
- Fast and easy integration of IoT applications
- User-friendly and standardized
- · High functionality due to OPC UA and CODESYS
- Manufacturer-independent software management to reduce maintenance efforts
- Variety of interfaces for a wide range of automation applications

CPU	Single Core with 1.0 GHz Optional: Dual and Quad Cortex-A9 (1.2 GHz)
RAM	up to 1 GB
Memory	4 GB
Expandable memory	SD card up to 64 GB
TFT display	7"
Resolution	1024×600
Touch	capacitive
Ethernet	10/100 Mbit/s
USB	2× USB 2.0
CAN	1× CAN interface acc. to ISO 11898, galv. isolated
EtherCAT	1× RJ45
Serial interface	1× RS 232
Digital input (optional)	4× DI, 24 V, max. input current 10 mA
Digital output (optional)	$4\times$ DO, 24 V, max. output current 1 A
Real time clock	integrated (buffered)
Protection class (front)	IP54
Protection class (back)	IP20
Dimensions	220 mm \times 280 mm \times 10 mm (without plug)
Storage temperature	0°C up to +60°C
Operating temperature	+5 °C up to +50 °C
Temperature sensor	integrated
Humidity	5 % up to 95 % non-condensing
Power supply	24 V DC ±20 %
Operating system	Linux

Pin assignment



RJ 45 Ethernet

1	LAN/EtherCAT_TX+
2	LAN/EtherCAT_TX—
3	LAN/EtherCAT_RX+
4	=
5	-
6	LAN/EtherCAT_RX—
7	-



IO clamp (optional

10 6	clamp (optional)
1	24V_I0
2	0V_I0
3	DI1
4	DI2
5	DI3
6	DI4
7	D01
8	D02
9	D03
10	D04



USB

1	USB 5V
2	USB D—
3	USB D+
4	USB 0V



CAN

1	CAN L (high)
2	CAN H (low)
3	CAN GND
4	=
5	=
6	=
7	CAN GND
0	



6

RS232

1	+
2	RxD
3	TxD
4	_
5	=
6	=
7	=
8	=
9	GND

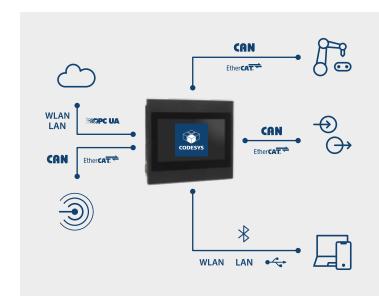


Power Supply

1	24V
2	0V
2	CND

Application example automation

IoT applications can be implemented with the state-of-the-art controller independently of the manufacturer and thus easily. The integration of OPC UA and CODESYS, among others, makes this possible.





Order information

V966372000 eControl micro II



eControl mIO

The eControl mIO convinces as an all-round package with numerous communication interfaces. Equipped with the PLC, a large number of small machines do not require any further IO modules. It provides you with targeted and cost-effective support for your control tasks – for example, for controlling stepper motors.

Key Features



7" touch display



1× Ethernet interface



Up to 24 IOs



2× stepper interface



Microcontroller ARM Cortex-A9



Integrated microSD slot up to 64 GB



Programming in Qt 5.11.3



Modularity and housing choice



1× CAN interface acc. to ISO 11898 (opt.)

At a glance

The system is equipped with a wide range of interfaces – including Ethernet, e.g. for connection to a host system. The interface package is rounded off by USB, digital and analog inputs and outputs, interfaces for temperature sensors and stepper motors. In addition, there is the option of WLAN, Bluetooth for wireless data transmission and CAN for universal use. The PLC has a powerful CPU and is programmed with the Qt development framework. A capacitive touch display makes operation user-friendly through high accuracy and multi-touch capability.

Benefits

- Modular through SMARC architecture
- · Application-friendly and standardized
- High potential for cost and cabling savings
- Loaded with interfaces for a wide range of automation applications
- · Equipment options WLAN, Bluetooth, CAN
- Aluminium housing or simple mounting option

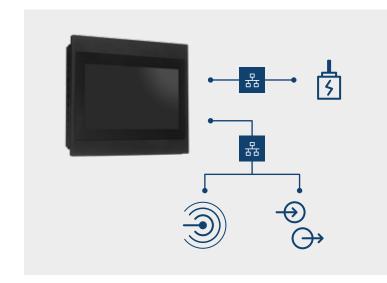
CPU	Single core with 1 GHz
RAM	up to 512 MB
Memory	4 GB
Expandable memory	microSD card up to 64 GB
TFT display	7"
Resolution	1024×600
Touch	capacitive
Ethernet	10/100 Mbit/s
USB	2× USB 2.0
CAN (optional)	1× CAN interface acc. to ISO 11898, galv. isolated
Dimensions (l×w×h)	182 mm × 117.5 mm × 8 mm
Storage temperature	0°C up to +60°C
Operating temperature	5°C up to +50°C
Humidity	5 % up to 95 %, non-condensing
Real-time-clock	integrated (buffered)
Protection class (front)	IP67
Power supply	24 V DC ±20 %
Operating system	Linux
IOs	
Digital inputs	4× DI, max. input current 10 mA
Digitale outputs	8× DO, max. output current 500 mA
Analoge inputs	$4\times$ AI ($2\times$ 0–10 V, $2\times$ 0–20 mA), 12 bit
Analoge outputs	$4\times$ AO (2× 0–10 V, 2× 0–20 mA), 10 bit
Stepper motor	2× interface, galv. isolated
Temperature sensor	2× PT100 input
Product labeling	
CE label	EN 61000-6-2 Electromagnetic compatibility (EMV) immunity EN 61000-6-4 Electromagnetic compatibility (EMV) emission

Development framework Qt and operating system Linux

The controller is programmed with the platform-independent development framework Qt 5.11.3. It is developed in C++ and libraries for a graphical user interface (GUI) are available. The allocation of a control library enables a very fast integration of stepper motors. The operating system used is Linux.

Application example automation

Control, operate and display – eControl mIO is the versatile controller with various fieldbus interfaces, IOs and motor interfaces for easy realization of automation requirements.



Pin assignment





RJ 45 Ethernet

1	LAN_TX+
2	LAN_TX-
3	LAN_RX+
4	=
5	=
6	LAN_RX-
7	=



CAN (optional)

1	CAN L (high)
2	CAN H (low)
3	CAN GND
4	=
5	-
6	=
7	CAN GND
8	_





USB

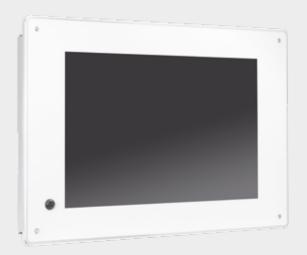
1	USB 5V	
2	USB D-	
3	USB D+	
	LICD 0	

Stepper Unit

1	Stepper 1/2 – winding 1+
2	Stepper 1/2 — winding 1—
3	Stepper 1/2 – winding 2+
4	Stepper 1/2 — winding 2 —

Order information

V966370250 eControl mIO



eControl mIO xt

Equipped with a variety of interfaces, the control with 10.1" touch display can be used for a wide range of automation applications. An integrated motion sensor makes it an energy miracle.

Key Features



Motion sensor



Up to 66 IOs



MDT 2.0 integrated



OPC UA Server & Client



2× CAN acc. to ISO 11898, galv. isolated



EtherCAT acc. to IEC 61158



2× Ethernet (100 Mbit/s, 1000 Mbit/s)



Linux operating system

Unbeatable Team with MDT 2.0

The Modular Diagnostic Toolchain with OPC UA can be integrated on the PLC, creating the perfect state-of-theart solution for your Industrie 4.0 applications. The new MDT® 2.0 provides a standardized tool to access data of the machine. It enables the standardization of data description (ODX), programming (OTX) and data sharing & provision (OPC UA). It is the perfect basis for innovative machine park monitoring. Combined with the eControl mIO xt, Sontheim creates the all-round package: smooth machine control, standardized diagnostics and simple cloud connection.

Variety of Interfaces

The eControl mIO xt is equipped with a number of interfaces. In addition to a motion sensor, the controller also has each two CAN, Ethernet, and USB connections as well as up to six temperature sensor inputs. One of the two Ethernet interfaces is EtherCAT and OPC UA capable. An interface board carries the digital inputs and outputs, as well as the majority of analog interfaces. All connectors are accessible from the rear side of the device.

Hardware	
CPU	I.MX 6 Quad Core
Co-Processors	2× ATXMEGA, 1× LPC433x
RAM	1 GB LPDDR2
Speicher	4 GB
Display	10.1" RGB 1280 (W) ×3(RGB) ×800(H) / 500 cd / IPS / anti-glare
Touch	resistive
LEDs	2 LEDs for display of power supply and CAN communication
Dimensions (l×w×h)	300 mm × 200 mm × 55 mm
Operating temperature	−20 °C up to +60 °C
Lagertemperatur	−30 °C up to +85 °C
Real-Time-Clock	2 weeks buffered via supercaps
Weight	approx. 2.1 kg
Protection class (front)	IP65
Protection class (back)	IP20
Power supply	24 V DC ±15 %

Interfaces	
Motion sensor	1× PIR Sensor
CAN	2× CAN acc. to ISO 11898, galv. isolated
USB	2× USB 2.0
Ethernet	2× (1× 100 Mbit/s: EtherCAT, OPC UA; 1× 1000 Mbit/s)
Digital inputs	24× DI (3×8), 24 V DC
Digital outputs	24× DO (3×8), 24 V DC
Analog inputs (optional)	10× AI, 16-bit, Output voltage range: 0 up to 10 V Output current range: 0 up to 20 mA
Analog outputs (optional)	4× AO, 16-bit Output voltage range: 0 up to 10 V
Temperature sensor inputs	4×24 -bit, optional up to $6 \times$
SD card slot	1x
Operating system	

Linux

opt.: MDT 2.0 embedded

Motion sensor

The pyroelectric sensor, or PIR sensor for short (Passive Infrared Sensor), reacts to movement and switches the display and backlight on as soon as movement is registered. This function is used to turn off the display and backlight when the device is not being operated and saves energy. The sensor is seamlessly integrated into the front panel.

EtherCAT and CAN Interfaces

Via the CAN and Ethernet interfaces you can configure the module for a CAN or EtherCAT network. As interfaces for data exchange it has two RJ45 sockets and one D-Sub9 CAN interface, which allows an easy connection with other modules.

Pin assignment

Operating system

Runtime



RJ 45 Ethernet 100 Mbit/s

1	LAN/EtherCAT_TX+
2	LAN/EtherCAT_TX-
3	LAN/EtherCAT_RX+
4	=
5	=
6	LAN/EtherCAT_RX-
7	-





CAN D-Sub9

2	CAN L (low)	
3	CAN GND	
5	CAN GND	
7	CAN H (high)	



RJ 45 Ethernet 1000 Mbit/s

1	D1+
	D1-
3	D2+
	D3+
	D3-
6	D2-
7	D4+
Q	D4_



USB

1	USB 5V	
2	USB D-	
3	USB D+	
4	USB OV	

Order information

V966373700	eControl mIO xt
V066373611	Clamp block



ePC

ePC is a modular embedded platform for being used in all areas of the automation sector. The design principle of bus-coupling devices allows extensions while the basic system remains untouched.

Key Features



Atom-CPU with passive cooling



Numerous interfaces like CAN, Ethernet, IOs, CFast, DVI and USB



Software tools for all tasks around the CAN bus



Link2Go: Extension modules can be attached without adapting the ePC like fieldbus couplers



IP20 full metal housing for optimum EMC protection

Main technical advantages

There are several different processor types of the Atom family available. The chipset is known for a high energy efficiency and little heat waste. It has 1 to 2 GB RAM onboard for small to complex operations. Instead of a usual HDD the ePC uses CFast which is the faster successor of Compact Flash – the system can also be booted over this interface. The advantage is a data transfer speed of up to 3 Gbit/s. Of course, all CFast cards can be purchased via Sontheim. A full metal housing together with the specific memory and CPU provides optimal EMC-capabilities and passive cooling even at high temperatures.

Link2Go - Expand your PC!

Modern automation applications require efficiency and the flexibility to adapt to changing environments in an individually matching way. Link2Go is a concept of adding extension modules quickly and conveniently to the ePC. However, the basic unit remains as it is and the user can change the modules later on if necessary. The range of the planned extensions varies from touch displays and bus couplers to hard disk drives and serial interfaces. There could even customer-specific modules be created. Link2Go – your personal embedded solution for the price of standard components.

Chipset	Freely selectable Atom-Chipsets, e.g. 1.3 GHz / 1 GB RAM CPU boards are exchangeable, new CPU platforms thus retrofittable
RAM	1–2 GB, optional separate process data storage (Retain storage)
HDD	Slot for CFast-Card or Link2Go module, bootable
CAN	1× CAN interface acc. to ISO 11898, galv. isolated
LAN	2× Gigabit LAN (one interface is EtherCAT-capable)
WLAN	optional
Digital Inputs	$4\times$ DI, acc. to IEC 61131-2, separate supply
Digital Outputs	$4\times$ DO, acc. to IEC 61131-2, separate supply
USB	4× USB 2.0
DVI-D	1x
Connection of external peripheral components	Mouse, keyboard and other peripherals via USB 2.0 Visualization via DVI or via Link2Go module
LEDs	Power, HDD and CAN
Dimensions (I×w×h)	120 mm × 115 mm × 111 mm
Storage temperature	−20°C up to +65°C
Operating temperature	0°C up to +60 $^{\circ}\text{C}$; extended temperature range with –40 $^{\circ}\text{C}$ up to +85 $^{\circ}\text{C}$
Humidity	5 % - 95 % non-condensing
Protection class	IP20
Power supply	24 V DC ±20 %
Total current	max. 1.2 A

Pin assignment





DVI-D

01	TDMS-data 2—
02	TDMS-data 2+
03	Shield TDMS-data 2.4
04	TDMS-data 4—
05	TDMS-data 4+
06	DDC frequency
07	DDC frequency
08	Analog: V-Sync
09	TDMS-data 1—
17	TDMS-data 0—
18	TDMS-data 0+
19	Shield TDMS-data 0.5
20	TDMS-data 5—
21	TDMS-data 5+
22	Shield TDMS-frequency
23	TDMS-data +
24	TDMS-data—
C1	NC
C2	NC
G	NC
C 4	NC
C5	NC





CAN

1	_
2	CAN low
3	CAN GND
4	=
5	-
6	=
7	CAN high
8	=
9	_



Digital IOs

1	24 V power supply
2	Digital input 0
3	Digital input 1
4	Digital input 2
5	Digital input 3
6	GND
7	Digital output 0
8	Digital output 1
9	Digital output 2
10	Digital output 2

111

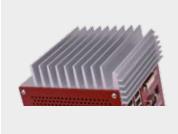
USB

1	VCC (VBUS)	
2	— Data	
3	+ Data	
4	GND (Ground)	

Interfaces

The ePC incorporates many interfaces for a maximum of flexibility already in its basic version without extensions (Link2Go). These includes CAN, Ethernet (EtherCAT capable), digital inputs and outputs, DVI and USB. In the basic configuration tasks as PLC, CAN bus master or slave, signal processing center and many more applications are possible. An integrated CFast interface like an USB stick thought for data logging and even booting the system.





Order information

V971011000

ePC



IPC-4

The IPC clearly sets itself apart from the competition with its scalable scope of performance. Both computing power and the type and number of interfaces offer many possibilities for individual adaptation.

Key Features



Significantly increased performance



Scalable power



Additional interfaces easily integrated



All interfaces accessible from the front



Very good performance even in harsh environments



Suitable for industrial use due to integrated power supply and fan

In its latest generation the IPC-4 combines the Sontheim know-how in state-of-the-art technology and integrated solutions. It is perfectly suited to all tasks in the automation and automotive industry. Due to its scaleable CPU, RAM, HDD and interfaces, you will have a PC that fits your application in every aspect. Both computing performance and number/type of interfaces offer various different versions. This creates a maximum of mudalirty and scalability. Of course, the housing is suitable for top hat rail mounting and allows access to all interfaces at the front cover, enabling comfortable handling and well-arranged cabling.

Scalable performance

The clock frequencies currently range from 600 MHz with an Intel Celeron M to 2×2.16 GHz with an Intel Core 2 Duo. Depending on the board type, up to 4 GB DDR RAM is used; thus, even computationally intensive tasks are possible without difficulty. An Intel Atom processor can be used as a power-saving variant.

Made for rough environments

The SATA HDDs used are approved for 24/7 operations. We are happy to switch to industrial temperature ranges for you. It is also possible to have devices with no rotating parts like Solid State Disks (SSD) which will guarantee you highest process reliability even in very rough environments.

Many interfaces in a compact design

The IPC-4 has six USB 2.0 ports, two Gigabit Ethernet (10/100/1000 BaseT), two serial interfaces as well as a DVI and a VGA connector. Additionally, there is a CF slot implemented. You will note that the device facilitates a clear arrangement of cabling with all interfaces being allocated at the front cover. The side parts are reserved for cooling fans and heat exhaust. Little cooling fins add up to controlling any heat.

Left side = standard, right side = flexible

Probably the most important advantage of the IPC-4 is its modular design that is suited for customer-specific extensions. PCI104 and PC104+ cards are up to most individual requirements like CAN, FireWire, digital and analog inputs and outputs, Framegrabber and many more functions.

32 KB battery buffered ZERO-RAM

The IPC will save runtime variables in this RAM memory for you in order to keep them in a case of a loss of power.





CPU Versions	600 MHz	1.5 GHz	2× 2.16 GHz
CPU	Intel Celeron M 600 MHz, ULV, 512 KB Cache, FSB 400 MHz	Intel Celeron M 370 1.5 GHz, 1 MB Cache, FSB 400 MHz	Intel Core 2 Duo T7400, 2.6 GHz, (4M Cache, 667 MHz FSB, 65 nm), socket mPGA479M
RAM	SO-DIMM DDR2 DDR5	33/ PC4200 up to 2 GB	2 socket, SO-DIMM DDR2 667/PC5300 up to 4 GB, 3 GB usable
Chipset	Graphics & memory controller hub: Intel 915GME IO controller hub: Intel 82801FBM (ICH6-M)		Graphics & memory controller hub: Intel 945GME IO controller hub: Intel 82801GHM (ICH7M-DH)
VGA resolution		Up to 2048×1536 (75 Hz)	

Interfaces	
Power/Watchdog	1× power supply, 1× relay, 1× remote
VGA	Depending on COM Express module (see CPU types)
DVI	1× DVI (resolution 640×480 up to 1600×1200, depending on display)
CF	CF-card acc. to specification 4.1 (CF UDMA Mode 0–4, PIO Mode 0–6)
USB Flash memory	Internal slot for Disk-on-Module flash memory via USB 2.0
Ethernet	LAN1 Gigabit Ethernet, Realtek RTL8111 10/100/1000 BaseT; LAN2 Intel 82573L 10/100/1000 BaseT interface, via PClexpress lane
USB	6× USB 1.1/2.0 up to 480 Mbit/s, power output 500 mA each
Serial interfaces	2× standard RS232 (with all handshake-signals), galvanic isolation optional (up to 2 kV)
PCI104 or PC104+	2× PCI104 or PC104+ slots for customer-specific interfaces
Optional PC104+ cards	CAN Bus FireWire Serial interfaces (RS232/RS485/RS422) PROFIBUS Framegrabber Digital/analog inputs and outputs Customer-specific functions

Hardware	
Status LEDs * please see the manual for further information	5 V – LED illuminated when connected to power supply Device ready for start/started* Run – shows operating status of the IPC-4* Err – Errors cause the error LED to blink* Rel – LED is illumintaed when relay adduct, turns off at dropout (Pin 12, 11 and 14) * HDD – shows the status of the internal HDD and the CF-card*
Buttons	SHDN – Start resp. automatic shutdown and power off, as long as ACPI is activated. Reset – Causes a warm boot
HDD	2.5" HDD (SATA or IDE up to 9.5 mm hight)
Support of periphery components via USB	CD-/DVD-ROM; CD-/DVD-RW; HDDs, USB-sticks, mouse and keyboard, other peripheral components
Certificates	EMC acc. to CE with EN 61000-6-4:2007, EN 55022:2006, EN 61000-6-2:2005, EN 61000-4-2:1995 + A1:1998 + A2:2001, EN 61000-4-3:2006, EN 61000-4-4:2004, EN 61000-4-5:2006, EN 61000-4-6:1996 + A1:2001 GL (on inquiry)
Dimensions (l×w×h)	244 mm (+10 mm minimum space to the left and right) \times 121 mm \times 95 mm (without connectors)
Housing	Compact aluminium case with integrated top hat rail (TS35)
Storage temperature	−20 °C up to +65 °C
Operating temperature	0° C up to +45 °C, optional -20 °C to +65 °C (with automotive HDD or Industrial CF-card and active cooling)
Humidity	5 % – 95 % non-condensing
Power supply	24 V DC \pm 20% (for standard versions) 24 V DC -25 % / $+30$ % (for GL-versions, German Lloyd) Power supply for automotive area available on enquiry
Power consumption at 24 V DC (without external periphery)	Max. power consumption 1.0 to 2.0 Start-up current 2.5 to 4.5 A
ower adaptor (integrated)	ATX – compatible, Wake-up via LAN supported

Pin assignment



RJ 45

	TI (D
1	TXD+
2	TXD—
3	RXD+
4	BIAS1
5	BIAS1
6	RXD—
7	BIAS2
8	BIAS2



VGA

1	Red
2	Green
3	Blue
13	HSync
14	VSync
12	DDC-Data
15	DDC-clock
9	5V
5-8,10	GND
4,11	NC



COM1

1	DCD
2	RXD
3	TXD
4	DTR
5	GND
6	DSR
7	RTS
8	CTS
9	RI



USB

1	VCC (VBUS)	
2	— Data	
3	+ Data	
4	GND (Ground)	



DVI

01	TDMS-data 2 —
02	TDMS-data 2+
03	Shield TDMS-data 2.4
04	TDMS-data 4 —
05	TDMS-data 4+
06	DDC frequency
07	DDC frequency
08	Analog: V-Sync
09	TDMS-data 1 —
17	TDMS-data 0 —
18	TDMS-data 0+
19	Shield TDMS-data 0.5
20	TDMS-data 5 —
21	TDMS-data 5+
22	Shield TDMS-frequency
23	TDMS-data +
24	TDMS-data —
(1	Analog: red
(2	Analog: green
G	Analog: blue
(4	Analog: H-Sync
C5	Analog: Mass
	•

Order information

V969000600	IPC-4; 600 MHz Intel Celeron M
V969001500	IPC-4; 1.5 GHz Intel Celeron M 370
V969002100	IPC-4; 2× 2.16 GHz Intel Core2Duo T7400
V990230000	IPC-4 Customizing



Panel-PC 8000

Panel-PC 8000 combines the flexibility of our industrial PCs with a rigid control and display panel. Due to its robust design, it is highly suited for machine control and HMI purposes.

Key Features



Robust terminal for the control of machines



Powerful and energy-saving Intel Atom processor



Expansion slots for individual adaption



Mounting arm attachment for flexible placement

Equipment and display

A 1.1 GHz Atom processor provides computing power at low energy consumption. There are 512 MB RAM available as well as an integrated SD-card with 2 GB for applications. The terminal contains a control and display panel for visualizing data and operating software tools. Consequently, Panel-PC 8000 is an ideal HMI.

Interfaces

The terminal provides two CAN channels with M12 plugs. External periphery like mouse or keyboard are simply connected via USB 2.0. It provides an ethernet port via M12 with a bandwith of 100 Mbit/s.

CPU	Intel Atom CPU 1.1 GHz
RAM	512 MB
Memory	Internal SSD ATA SolidStateDrive-Flash, 512 MB Internal SD-Slot with integrated 2 GB SD-card Other SD-cards available upon enquiry
CAN	2× CAN interface via 2× M12 connectors (2× female)
USB	2× USB 2.0, Type A
Ethernet	1× Ethernet, 100 Mbit/s, M12
Supported CAN interfaces	CANUSB, CANfox®, others upon enquiry
Display	7"
Resolution	800×480, 262 colors
Touch	resistive
Touch Surface	Anti glare and wide view
	Tesistite
Surface	Anti glare and wide view
Surface Buttons/Front foil	Anti glare and wide view 19 buttons incl. keypad and navigation
Surface Buttons/Front foil LEDs	Anti glare and wide view 19 buttons incl. keypad and navigation 2 LEDs for monitoring current supply errors
Surface Buttons/Front foil LEDs Dimensions (lxwxh)	Anti glare and wide view 19 buttons incl. keypad and navigation 2 LEDs for monitoring current supply errors 308 mm × 283 mm × 80 mm
Surface Buttons/Front foil LEDs Dimensions (lxwxh) Storage temperature	Anti glare and wide view 19 buttons incl. keypad and navigation 2 LEDs for monitoring current supply errors 308 mm × 283 mm × 80 mm -10 °C up to +55 °C
Surface Buttons/Front foil LEDs Dimensions (lxwxh) Storage temperature Operating temperature	Anti glare and wide view 19 buttons incl. keypad and navigation 2 LEDs for monitoring current supply errors 308 mm × 283 mm × 80 mm -10 °C up to +55 °C 0 °C up to +45 °C
Surface Buttons/Front foil LEDs Dimensions (lxwxh) Storage temperature Operating temperature Weight	Anti glare and wide view 19 buttons incl. keypad and navigation 2 LEDs for monitoring current supply errors 308 mm × 283 mm × 80 mm -10 °C up to +55 °C 0 °C up to +45 °C 3.0 kg
Surface Buttons/Front foil LEDs Dimensions (lxwxh) Storage temperature Operating temperature Weight Housing	Anti glare and wide view 19 buttons incl. keypad and navigation 2 LEDs for monitoring current supply errors 308 mm × 283 mm × 80 mm -10 °C up to +55 °C 0 °C up to +45 °C 3.0 kg Plastic housing with support arm mount
Surface Buttons/Front foil LEDs Dimensions (lxwxh) Storage temperature Operating temperature Weight Housing Rel. Humidity	Anti glare and wide view 19 buttons incl. keypad and navigation 2 LEDs for monitoring current supply errors 308 mm × 283 mm × 80 mm -10 °C up to +55 °C 0 °C up to +45 °C 3.0 kg Plastic housing with support arm mount 5 % – 95 % non-condensing

Flexibility via PCI extensions

The two extension slots enable an integration of additional extensions. There are many different versions of extension cards available, much like our IPC-4: CAN, FireWire, digital and analog inputs and outputs, PROFI-BUS and many more functions can be integrated for a customer-specific solution. Panel-PC 8000 can therefore be used as a standard-HMI or as an individually tailored control system.

Robust design

HMIs in production facilities might be exposed to temperature changes, splash water and mechanical forces. Panel-PC 8000 is designed to withstand such effects with the help of a robust design. No water can enter the housing. All connectors have an inward barrier. The foil keyboard with extra large buttons is made for bigger gloves. Finally, a wall mount arm can be used for having the terminal mounted outside of a control cabinet.

Pin assignment



USB

- 1 VCC (VBUS)
- 2 Data 3 + Data 4 GNP
- GND (Ground)



CAN 1 with VCC

- CAN GND
- 24 V ±20 % Supply voltage
- 3 OV Supply voltage
- CAN High



CAN 2

- 1 CAN GND
- 3
- CAN H (high) CAN L (low)



Ethernet

- 1 Tx+ (transmit data +)
- Rx+ (receive data +)
- 3 Tx— (transmit data —) Rx— (receive data —)
- 5 Connector thread is shield



Order information

V970001000

Panel-PC 8000



Digital Remote IO-Modules

DIO32 is a digital 24V (opt. 12V) input and output module with 16 channels each. It is optimally suited for the use in CAN networks. The device possesses the shortest conversion times and a high process reliability. That makes it the best choice for continuous operation in complex machine networks.

Key Features



Safety features for high running safety



Galv. isolated CAN interface acc. to ISO 11898



Easy access to all interfaces



Own intelligence for complex CAN networks



All clamps pluggable and lockable



Signal delay of less than 400 μs



Galv. isolated inputs



Compact aluminium housing with IP20 and integrated top hat rail mounting

Overview of interfaces

- 16 digital inputs
- 16 digital outputs

Housing

The compact housing is made of aluminium. It contains a top hat rail mount and a front cover with all interfaces for better overview in the control cabinet. The technician will note the convenience while working at the bus cabling.

Clamps and cabling

The Remote-IO series uses 3-wire cabling for direct connection to sensors and actors, supplying them with power. In order to reduce the danger of false-wire harnessing the 3-wire clamps are colored. If you wish to see the status of each channel, we can deliver the modules with LED-clamps.

LEDs and switches

All inputs and outputs can be monitored with the help of LEDs at the clamps. In addition to that, you can configure the baud rate and module address with HEX switches at the front cover – easy and comfortable.

Signal processing

Besides its inputs and outputs the DIO32 offers a powerful microcontroller that handles data acquisition of sensors, control of actors and the processing of any CAN data. An important safety function is the DIO32's guarding capability which is fully integrated into the IO for network surveillance. Furthermore, there is a relay contact (changeover) as an additional safety measure. If there is an absence of guarding by the master registered, the module immediately goes into STOP-mode.

CAN interface

The integrated CAN interface is designed in accordance to DS301 and 401 for a flexible use in different places and tasks in the CAN bus network. All Sontheim CAN interfaces comply to ISO 11898.

Power supply

The DIO32 needs a power supply with 24 V. Due to the polarity reversal protection the user is in no danger of damaging the module by reversed power connection. Short surge peaks are also eliminated by an EMI wiring for the control section.

Highside and Lowside switch

All digital outputs can be fitted with a Highside or Lowside switch. Being Highside, the outputs toggle the supply voltage to load. Being Lowside, they toggle to ground.

DI32 DO32 DIO32







DI040 DI072



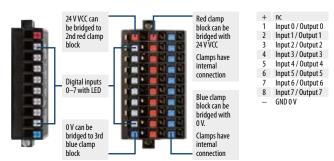




Commercial procession Campaign gange 0.73 - 1.5 mm² Camp	Hardware	DI32	DO32	DIO32	DI40	DIO40	DIO72
Commercial Control of State Comm	CPU			16-bit mic	rocontroller		
Particular of modulaschius	CAN	Galvanically isolated acc. to ISO 11898, D-Sub9 plug male and female, bridged; Assignment acc. to DIN 41652					
Commention system Clamping range 0.5 - 15 mm², solid wite "st. The vivine" 1" 0.25 - 15 mm² with blust splastic coller 0.25 - 15 mm² Commention system Clamping range 0.5 - 15 mm², solid wite "st. The vivine" 1" 0.25 - 15 mm² " with where and ferrule, without plastic coller 0.25 - 15 mm² Commention sechnology Towner supply (DV) For prover supply (DV) For pro	CAN protocol	DS 301 and 401					
Connection system Clamping range 0.25 – 1.5 mm², valid wire**; Fine vier**12.5 – 1.5 mm², ** roth wire and femule, without plastic collar 0.25 – 1.5 mm² Connection technology To write and three vier connection, stripping length 10 mm. In ED green for power supply (v)) In ED green for power supply (v)) In ED green for power supply (v)) In ED green for power supply (v) In	Number of modules/bus	127					
Connection system	Setting						
International Characteristics International Characteristic	Connection system	clamping ra	ange 0.25 – 1.5 mm², solid w			rrule, without plastic collar	· 0.25 – 1.5 mm²
12 E.D geren for power supply (SV) To LED geren	Connection technology		Tw	ro-wire and three-wire con	nection, stripping length 1	0 mm	
Page	Operating status	for power supply (5V) 1× LED green for operation mode (Run) 1× LED red for error status (Err) 32× LED green	for power supply (5V) 1x LED green for operation mode (Run) 1x LED red for error status (Err) 32x LED green for set outputs (at the	for power supply (5V) 1x LED green for operation mode (Run) 1x LED red for error status (Err) 16x LED green for set inputs 16x LED green for set outputs (at the	for power supply (5V) 1× LED green for operation mode (Run) 1× LED red for error status (Err) 40× LED green	for power supply (5V) 1× LED green for operation mode (Run) 1× LED red for error status (Err) 32× LED green for set inputs 8× LED green for set outputs (at the	for power supply (5V) 1× LED green for operation mode (Run) 1× LED red for error status (Err) 32× LED green for set inputs 40× LED green for set outputs (at the
P 20, EMC requirements acc. to CE	Dimensions (l×w×h)			121 mm × 120 mm × 48 mm			241 mm × 120 mm × 48 r
P 20, EMC requirements acc. to GE	Veight			600 g			800 g
Departing temperature	-			· ·	rements acc. to CE		J
Departing temperature				•			
Add							
24 V DC ±20 % 25 V Hz 25 V Hz 25 V Hz 26 V Hz 2	, ,			,			
All inputs/outputs active, nct. LEDs S40 mA 440 mA 500 mA 540 mA	,				· ·		
Digital inputs Di32 Di32 Di032 Di40 Di040 Di072				24 V D	C ±20 %		
Number of inputs 32 - 16 40 32 Switching level "1" +15.0V up to +28.8V DC - +15.0V up to +28.8V DC	All inputs/outputs active, incl. LEDs	540 mA	440 mA	500 mA	540 mA	500 mA	830 mA
Switching level "I"	Digital inputs	DI32	DO32	DIO32	DI40	DIO40	DI072
Switching level*0* 0.0 V up to +8.0 V DC 0.0 V up to +8.0 V DC	Number of inputs	32	-	16	40	3	32
Potential isolation Optocoupler - Optocoupler - Optocoupler - III mA - III	Switching level "1"	+15.0 V up to +28.8 V DC	-		+15.0 V up	to +28.8 V DC	
Input current/input 11 mA - 11 mA - 2.5 kHz inpuling frequency (Fg) 2.5 kHz - 2.5 kHz - 2.5 kHz inpuling frequency (Fg) 2.5 kHz - 2.5 kHz - 2.5 kHz inpuling frequency (Fg) 2.5 kHz -	switching level "0"	0.0 V up to +8.0 V DC	_		0.0 V up 1	to +8.0 V DC	
Sampling frequency (Fg) 2.5 kHz - 2.5 kHz Signal delay - 400 µs	Potential isolation	Optocoupler	-		Opto	ocoupler	
Signal delay Company	nput current/input	11 mA	-		11	l mA	
Digital outputs DI32 DI32 DI32 DI032 DI040 DI040 DI072 Number of outputs - 32 16 - 8 40 Power - 24 V DC ±20 % - 24 V DC ±20 % FET-Highside-Switch Potential isolation - Optocoupler - Optocoupler - Optocoupler - 1A (short circuit proof) Total current of the Module with blockwise supply - 32 A 16 A - 8 A FOTAL current of the Module with blockwise supply - 32 A 16 A - 8 A Fotal current of the Module with blockwise supply - Wes, controlled inductors require external freewheel diodes - Yes, controlled inductors require external freewheel diodes - Selay contact - Wes, controlled inductors require external freewheel diodes - Wes, controlled inductors require external freewheel diodes - Selay contact	Sampling frequency (Fg)	2.5 kHz	_		2.:	5 kHz	
Number of outputs - 32 16 - 8 40 Power - 24 V DC ±20 % - 24 V DC ±20 % Circuit type - FET-Highside-Switch - FET-Highside-Switch Potential isolation - Optocoupler - Optocoupler Output current/output - 1A (short circuit proof) - 1A (short circuit proof) Fotal current of the Module - 8 A - 8 A Fotal current of the Module with blockwise supply - 1A kHz - 1 kHz Freewheel diode - Yes, controlled inductors require external freewheel diodes Freewheel diode - 100 µs Felay contact	Signal delay						
Power - 24 V DC ±20 % - 24 V DC ±20 % Circuit type - FET-Highside-Switch - FET-Highside-Switch Potential isolation - Optocoupler - Optocoupler Output current/output - 1A (short circuit proof) - 1A (short circuit proof) Total current of the Module - 8 A - 8 A Total current of the Module - 32 A 16 A - 8 A Ferewheel diode - 1kHz - 1kHz Freewheel diode - Yes, controlled inductors require external freewheel diodes Freewheel diode - 100 μs Relay contact	Digital outputs	DI32	DO32	DIO32	DI40	DIO40	DI072
FET-Highside-Switch Optocoupler Optocoupler I A (short circuit proof) Output current/output I A (short circuit proof) Output current of the Module Fotal current of the Module With blockwise supply Ferewheel diode Yes, controlled inductors require external freewheel diodes Ferewheel diode PET-Highside-Switch Optocoupler I A (short circuit proof) I A (short circuit proof) A B A B A B A Fotal current of the Module With blockwise supply Ferewheel diode Ferewheel diode Ferewheel diode Ferewheel diodes	Number of outputs	-	32	16	-	8	40
Potential isolation - Optocoupler - Optocoupler Output current/output - 1A (short circuit proof) - 1A (short circuit proof) Output current of the Module - 8 A - 8 A Outal current of the Module - 32 A 16 A - 8 A 40 A Switching frequency - 1kHz - 1kHz Freewheel diode - Yes, controlled inductors require external freewheel diodes Signal delay - <100 Selay contact SkilM/14 A SkilM/14 A	Power	_	24 V D0	C ±20 %	-	24 V [OC ±20 %
Potential isolation – Optocoupler – Optocoupler Dutput current/output – 1A (short circuit proof) – 1A (short circuit proof) Total current of the Module – 8 A – 8 A Total current of the Module – 32 A 16 A – 8 A 40 A Switching frequency – 1kHz – 1kHz Freewheel diode – Yes, controlled inductors require external freewheel diodes Freewheel diodes – 100 µs Relay contact	Circuit type	-	FET-Highs	ide-Switch	-	FET-High	side-Switch
Dutput current/output - 1A (short circuit proof) - 1A (short circuit proof) Fotal current of the Module - 8 A - 8 A Fotal current of the Module - 32 A 16 A - 8 A Fotal current of the Module with blockwise supply - 32 A 16 A - 8 A 40 A Fowitching frequency - 1kHz - 1kHz Freewheel diode - Yes, controlled inductors require external freewheel diodes - 100 µs Felaly contact - 100 µs	Potential isolation	-	-		_	_	
Fotal current of the Module Fotal current of the Module F	Output current/output	_			-	1 A (short	circuit proof)
Fotal current of the Module with blockwise supply - 32 A 16 A - 8 A 40 A Switching frequency - 1 kHz - 1 kHz Freewheel diode - Yes, controlled inductors require external freewheel diodes - 100 µs Selay contact - 100 µs		_		•	_		
Freewheel diode - Yes, controlled inductors require external freewheel diodes - Yes, controlled inductors require external freewheel diodes - Yes, controlled inductors require external freewheel diodes - 100 µs - 100 µs	Total current of the Module with blockwise supply	-			-		
Freewheel diodes - freewheel diodes - freewheel diodes Signal delay - <100 μs - <100 μs Relay contact	Switching frequency	-	1 k	Hz	-	1	kHz
Relay contact 15/1M/1A 15/1M/1A	Freewheel diode	-			-		
	Signal delay	-	< 10	00 μs	-	<1	100 μs
	Relay contact (if module is active)	-	1× UM	M/1A	-	1× L	JM / 1 A

Pin assignment

Clamp block





CAN D-Sub9





HEX-Switches module adress

Minimum 01 HEX	1
Maximum 7F HEX	127



HEX-Switch baud rate

0	10
1	20
2	50
3	125
4	250
5	500
6	800
7	1000

Order information

V966117000	DI32 RM35 24 V IO
V966117400	DI32_RM35 12 V IO
V966127000	DO 32_RM35 24 V IO High-Side
V966127300	DO 32_RM35 12 V IO High-Side
V966127400	DO 32_RM35 12 V IO Low-Side
V966160000	DIO 32_RM35 24 V IO High-Side
V966160300	DIO 32_RM35 12 V IO High-Side
V966160400	DIO 32_RM35 12 V IO Low-Side
V966181000	DI40_RM35
V966180000	DIO40_RM35, 32× dig.ln. & 8× dig. Out 24 V IO
V966170000	DIO 72_RM35 24 V IO High-Side
V966170300	DIO 72_RM35 12 V IO High-Side
V966170400	DIO 72_RM35 12 V IO Low-Side
V980109000	Weidmüller BL IO-30-pole with LED (not included in delivery)
V980109100	Weidmüller BL IO-30-pole without LED (not included in delivery)
V980109200	Weidmüller BL IO-10-pole with LED (not included in delivery)
V980109300	Weidmüller BL IO-10-pole without LED (not included in delivery)



Multi-IO

The CANopen module Multi-IO is a powerful device for handling digital and analog signals. It incorporates 56 channels of different communication channels. The device possesses the shortest conversion times and a high process reliability. That makes it the best choice for continuous operation in complex machine networks.

Key Features



Safety features for high running safety



Galv. isolated CAN interface acc. to ISO 11898



Easy access to all interfaces



Own intelligence for complex CAN networks



All clamps pluggable and lockable



Signal delay of less than 200 µs



Galv. isolated inputs



Compact aluminium housing with IP20 and integrated top hat rail mounting

Overview of interfaces

- 16 digital inputs
- 16 digital outputs
- 8 analog inputs
- 8 analog outputs
- four 24-bit encoder interfaces
- one CAN interface

Housing

The compact housing is made of aluminum. It contains a top hat rail mount and a front cover with all interfaces for better overview in the control cabinet. The technician will note the convenience while working at the bus cabling.

Clamps and cabling

Using the 3-wire connection technology, all sensors and actuators can be connected directly to the module. The danger of incorrect wiring is greatly reduced by the color coding of the potentials, even for less experienced users. Various terminal strips are available, which are optionally equipped with LEDs. However, these should only be used for digital inputs and outputs.

LEDs and switches

All inputs and outputs can be monitored with the help of LEDs at the clamps. In addition to that, you can configure the baud rate and module address with HEX switches at the front cover – easy and comfortable.

Signal processing

Besides its inputs and outputs the Multi-IO offers a powerful microcontroller that handles data acquisition of sensors, control of actors and the processing of any CAN data. An important safety function is the Multi-IOs guarding capability which is fully integrated into the IO for network surveillance. Furthermore, there is a relay contact (changeover) as an additional safety measure. If there is an absence of guarding by the master registered, the module immediately goes into STOP-mode.

CAN interface

The integrated CAN interface is designed in accordance to DS 301 and 401 for a flexible use in different places and tasks in the CAN bus network. All Sontheim CAN interfaces comply to ISO 11898.

Power supply

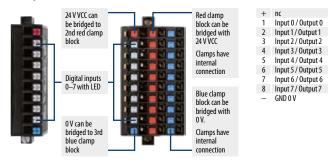
The Multi-IO is supplied with 24 V. The integrated reverse polarity protection prevents possible destruction of the IO mode if the supply voltage is incorrectly applied. The control section is additionally protected against short overvoltage peaks by an EMC circuit on the supply voltage.

Highside and Lowside switch

All digital outputs can be fitted with a Highside or Lowside switch. Being Highside, the outputs toggle the supply voltage to load.

Pin assignment

Clamp block









CAN D-Sub9

1	-
2	CAN low
3	CAN GND
4	=
5	-
6	=
7	CAN high
8	=
9	-

HEX-Switches module adress

Minimum 01 HEX	1
Maximum 7F HEX	127



HEX-Switch baud rate

0	50
1	125
2	250
3	500
4	1000

Hardware	
CPU	Motorola MC9S12DP256B
CAN interface	1× CAN acc. to ISO 11898, galv. isolated
CAN protocol	DS 301 and 401
Terminal block	Connection wire Ø 0.25 mm ² up to 1.5 mm ²
Operating system display	1× LED green for supply voltage (5 V) 1× LED green for operating mode (Run) 1× LED red for error status (Err)
Dimension (l×w×h)	241 mm × 120 mm × 48 mm
Weight	approx. 800 g
Protection class	IP20
Storage temperature	–10 °C up to +70 °C
Operating temperature	0°C up to +60°C
Humidity	90 % non-condensing
Power supply	24 V DC ±20 %
Power consumption	approx. 500 mA

Digital inputs	
Number of inputs	16
Circuit type	positive switching inputs
Potential isolation	Optocoupler
Display (directly at the clamp)	LED (green) for set inputs
Switching level "1"	+15.0 V up to +28.8 V
Switching level "0"	0.0 V up to +8.0 V
Input current/input	8 mA
Signal delay	< 200 μs

Digital outputs	
Number of outputs	16
Circuit type	FET-Highside switch
Potential isolation	Optocoupler
Output voltage	Supply voltage – approx. 0.3 V
Display (directly at the clamp)	LED (green) for activated output
lout Max	1 A
Sampling frequency	1 kHz
Short circuit resistance	Yes
Freewheel diodes	Yes, each activated coil must be provided with a freewheel diode
Signal delay	< 100 µs

Analog inputs	
Number of inputs	8, together galv. isolated
Resolution	12 bit
Potential isolation	Optocoupler
Input voltage	–10 V up to +10 V DC
Sampling frequency	Up to max. 12 analog inputs in operation: 1 kHz more than 12 analog inputs in operation: 500 Hz

Analog outputs	
Number of outputs	8, together galv. isolated
Resolution	12 bit
Potential isolation	Optocoupler
Output voltage	-10 V up to +10 V DC
lout Max	20 mA
Filter circuitry	integrated

Encoder-inputs	
Number of inputs	4
Level	RS485 (A and B)
Max. input frequency	300 kHz
Input voltage	5 V (to supply the encoder)
lout Max	80 mA (to supply the encoder)
Galvanic isolation	Optocoupler

Order information

V966105000	Multi-IO_RM35 24 V IO High-Side
V966105300	Multi-IO_RM35 12 V IO High-Side
V966105400	Multi-IO_RM35 12 V IO Low-Side
V980109000	Weidmüller BL IO-30-pole with LED (not included in delivery)
V980109100	Weidmüller BL IO-30-pole without LED (not included in delivery)
V980109200	Weidmüller BL IO-10-pole with LED (not included in delivery)
V980109300	Weidmüller BL IO-10-pole without LED (not included in delivery)



We live electronics – and also quality. That's why we set ourselves the goal of implementing it in every area. We create customer satisfaction through a holistic quality culture for the company, processes, products and services. We want to create real added value for our customers and maintain and build long-term relationships. The basic prerequisite for this is consistently high quality – based on standards and certifications.





Super-IO

Super-IO is a digital 24 V input and output module with 160 digital inputs and 192 digital outputs. It is optimally suited for the use in CAN networks. The device possesses the shortest conversion times and a high process reliability. That makes it the best choice for continuous operation in complex machine networks.

Key Features



Safety features for high running safety



Galv. isolated CAN interface acc. to ISO 11898



Easy access to all interfaces



Own intelligence for complex CAN networks



All clamps pluggable and lockable



Signal delay of less than 400 µs



Galv. isolated inputs



Compact aluminium housing with IP20 and integrated top hat rail mounting

Overview of interfaces

- 160 digital inputs, divided into 5 blocks of 32 channels
- 192 digital outputs, divided into 6 blocks of 32 channels

Housing and clamps

The compact housing is made of aluminium. It contains a top hat rail mount and a front cover with all interfaces for better overview in the control cabinet. The technician will note the convenience while working at the bus cabling. The module uses very robust clamps and cabling for the connection to sensors and actors. In order to maximize the resistivity against mechanical force, all clamps can be locked.

LEDs and switches

You can configure the baud rate and module address with HEX switches at the front cover – easy and comfortable. Moreover, there is a 7-segment display as well as some LEDs for showing the device status.

Hardware	
CPU	16-bit microcontroller
CAN	1× CAN acc. to ISO 11898, galvanically isolated; Connection with two RJ45 socket (bridged)
CAN protocol	DS 301 and 401
Setting	of module address via 2 HEX switches of baud rate via HEX switch
Connection system	D-Sub50 clamp, lockable
Operating system display	1× LED green (run) for operating mode 1× LED red (error) for error status 1× LED green (power) for supply voltage 1× 7-Segment display for module activities like Init, Pre-Operational, Operational and error
Dimensions (l×w×h)	240 mm × 125 mm × 90 mm
Protection class	IP20, EMC-requirements according to CE
Storage temperature	−30°C up to +70°C
Operating temperature	0°C up to +60°C
Humidity	90 % non-condensing
Power supply	24 V DC ±20 %

Digital inputs	
Number of inputs	160
Switching level "1"	+15.0 V up to +28.8 V
Switching level "0"	0.0 V up to +8.0 V
Potential isolation	Optocoupler
Input current/input	11 mA
Sampling frequency (Fg)	5 kHz
Signal delay	< 100 μs
Digital outputs	
Number of ouputs	192
Power	24 V DC ±20 %
Circuit type	FET-Highside switch
Potential isolation	Optocoupler
Output current/output	500 mA
Total current of the module	8 A

Signal processing and CAN interface

Besides its inputs and outputs the Super-IO offers a powerful microcontroller that handles data acquisition of sensors, control of actors and the processing of any CAN data. An important safety function is the guarding capability which is fully integrated into the IO for network surveillance. If there is an absence of guarding by the master registered, the module immediately goes into STOP-mode. The integrated CAN interface is designed in accordance to DS 301 and 401 for a flexible use in different places and tasks in the CAN bus network. All Sontheim CAN interfaces comply with ISO 11898.

Customized adaptations

Quite often, the specific requirements of an automation process make it necessary to have an IO module meeting individual needs. This is particularly the case for the number and type of in- and outputs, the fieldbus, the current supply of the module and IO channels and many more details. It is our pleasure to adapt the module to your processes.

Order information

V966185000

Super-IO



IAO08

The analog output module IAO08 is a powerful device for forwarding analog signals. The device possesses the shortest conversion times and a high process reliability. That makes it the best choice for continuous operation in complex machine networks.

Key Features



Safety features for high running safety



Galv. isolated CAN interface acc. to ISO 11898



Easy access to all interfaces



Own intelligence for complex CAN networks



Signal delay of less than 400 µs



Galv. isolated inputs



Compact aluminium housing with IP20 and integrated top hat rail mounting

Housing

The compact housing is made of aluminium. It contains a top hat rail mount and a front cover with all interfaces for better overview in the control cabinet. The technician will note the convenience while working at the bus cabling.

Switches

You can configure the baud rate and module address with HEX switches at the front cover – easy and comfortable.

Signal processing

Besides its outputs the IAO08 offers a powerful microcontroller that handles the control of actors and the processing of any CAN data. An important safety function is its guarding capability which is fully integrated into the IO for network surveillance. Furthermore, there is a relay contact (changeover) as an additional safety measure. If there is an absence of guarding by the master registered, the module immediately goes into STOP-mode.

CAN interface

The integrated CAN interface is designed according to DS 301 and 401 for a flexible use in different places and tasks in the CAN bus network. All Sontheim CAN interfaces comply to ISO 11898.

Hardware	
CPU	16-bit microcontroller
CAN	1× CAN acc. to ISO 11898, galv. isolated
Operating system display	1× LED green for supply voltage (5 V) 1× LED green for operating mode (run) 1× LED red for error status (err)
Dimensions (l×w×h)	241 mm × 120 mm × 48 mm
Weight	ca. 800 g
Protection class	IP20
Storage temperature	−10 °C up to +70 °C
Operating temperature	0°C up to +60°C
Humidity	90 % non-condensing
Power supply	24 V DC ±10 %
Total current	approx. 500 mA

Analog outputs	
Number of outputs	8
Resolution	12 bit
Potential isolation	Optocoupler
Output voltage	-10 V up to +10 V DC
lout max	20 mA
Filter circuitry	integrated

Pin assignment



Analog outputs

1	-
2	=
3	=
4	ANAOUT
5	ANAOUT
6	ANAGND
7	ANAGND
8	=
9	GND



HEX-Switch baud rate

0	50	
1	125	
2	250	
3	500	
4	1000	



CAN interface

1	CAN H (high)
2	CAN L (low)
3	GND

Order information

V966301000 IAO08 – 8× AnaOut



IDX 32

IDI32 is a digital 32-channel 24 V input module for the use in CAN networks. The device possesses the shortest conversion times and a high process reliability. That makes it the best choice for continuous operation in complex machine networks.

Key Features



Safety features for high running safety



Galv. isolated CAN interface acc. to ISO 11898



Easy access to all interfaces



Own intelligence for complex CAN networks



Signal delay of less than 400 µs



Galv. isolated inputs



Compact aluminium housing with IP20 and integrated top hat rail mounting

Clamps and cabling

A very important feature of the IDI32 in its different versions is the really sturdy way in which the connection of actors and sensors is handled. 24 V, data and GND have separate connectors (3-wire-connection). We use phoenix clamps for simple and rugged connections. Every IO-block of the device is galvanically isolated and has its own power supply. Thus, all IDxx modules can be used in safety-relevant environments. An example for a typical application is the CAN handling of emergency-stop circuits like guard doors.

CAN interface

Two RJ45 connectors at the front cover facilitate the connection with other CAN participants over ethernet patch cable. The IDI32 can also be used in a decentralised CAN network.

LEDs and switches

All inputs and outputs can be monitored with the help of LEDs at the clamps. In addition to that, you can configure the baud rate and module address with HEX switches at the front cover – easy and comfortable.

Hardware	IDI32	ID032	IDIO32
CPU	16-bit microcontroller		
CAN	Galvanically isolated acc. to ISO 11898, connection via two RJ45 connectors (bridged)		
CAN protocol	DS 301 and 401		
Number of modules/bus		127	
Setting	of module address via 2 HEX-switches of baud rate via HEX-switch		
Connection system	Spring connection clamping range 0.25 – 1.5 mm², solid wire "e", fine wire "f" 0.25 – 1.5 mm², "f" with wire end ferrule, without plastic collar 0.25 – 1.5 mm²		
Connection technology	Two-wire ar	nd three-wire connection, stripping le	ngth 10 mm
Operating status display	1× LED green for power supply (5V) 1× LED green for operation mode (Run) 1× LED red for error status (Err) 32× LED green for set inputs	1× LED green for power supply (5V) 1× LED green for operation mode (Run) 1× LED red for error status (Err) 32× LED green for set outputs (at the clamp)	1× LED green for power supply (5V) 1× LED green for operation mode (Run) 1× LED red for error status (Err) 16× LED green for set inputs 16× LED green for set outputs (at the clamp)
Dimensions (l×w×h)	241 mm × 120 mm × 48 mm		
Weight	850 g		
Protection class	IP 20, EMC-requirements acc. to CE		
Operating temperature	0°C up to +60°C		
Storage temperature	−30 °C up to +70 °C		
Humidity	90 % non-condensing		
Power supply	24 V DC ±20%		
All inputs/outputs active, incl. LEDs	400 mA 470 mA		

Digital inputs	IDI32	IDO32	IDIO32
Number of inputs	32	-	16
Switching level "1"	+15.0 V up to +28.8 V DC	+	+15.0 V up to +28.8 V DC
Switching level "0"	0.0 V up to +8.0 V DC	=	0.0 V up to +8.0 V DC
Potential isolation	Optocoupler	+	Optocoupler
Input current/input	11 mA	=	11 mA
Sampling frequency (Fg)	2.5 kHz	+	2.5 kHz
Signal delay	< 400 μs	-	< 400 μs

Digital outputs	IDI32	IDO32	IDIO32
Number of outputs	=	32	16
Power	-	24 V DC	E ±20 %
Circuit type	-	FET-Highsi	de-Switch
Potential isolation	=	Optoc	oupler
Output current/output	-	1 A (short circuit proof)	
Total current of the Module	-	8	A
Total current of the Module with blockwise supply	=	16	A
Switching frequency	-	1 k	Hz
Freewheel diodes	-	Yes, controlled induc freewhee	tors require external el diodes
Signal delay	-	< 10	0 μs

Pin assignment



9-pole phoenix clamp

Top	connector 24 V
1	24 V
2	Input 1 / Output 1
3	Input 2 / Output 2
4	Input 3 / Output 3
5	Input 4 / Output 4
6	Input 5 / Output 5
7	Input 6 / Output 6
8	Input 7 / Output 7
Bottom connector 0 V	



CAN RJ 45

1	_
2	=
3	-
4	CAN low
5	CAN high
6	=
7	CAN GND
8	_



HEX-Switches module adress

Minimum 01 HEX	1
Maximum 7F HEX	127



HEX-Switch baudrate

0	10	
1	20	
2	50	
3	125	
4	250	
5	500	
6	800	
7	1000	

Order information

V966116000	IDI32
V966126000	IDO32
V966128000	IDIO32



eControl-IO

The key to lean fieldbus networks and efficient process automation is flexibility. The user must be able to cope with rapidly changing process requirements with existing resources. The eControl IO-module was developed specifically for the use in machine networks and with its numerous expansion modules it provides many applications in industrial environments and is the ideal supplement for all PLCs of the eControl family.

Key Features



CANopen acc. to CiA Draft Standard DS 301 and 401



Fast in- and outputs, short signal delay



CAN baud rate up to 1 Mbit/s



Numerous expansion options (up to 6 expansion modules)



Compact aluminium housing with IP20 and integrated top hat trail mounting

Master module and CAN interface

The master module is the basis of the eControl IO module and is required in each constellation. The entire IO system is controlled by an integrated microcontroller, while already 16 digital outputs, 16 digital inputs, two analog outputs and two analog inputs are integrated. The module has an LED status indicator to show the status of the module and the switching states of the digital IOs. As an interfaces for data exchange, it has two RJ45 ports for the CAN bus which allows an easy and fast connection. Via DIP switch the module ID and baud rate of the CAN bus can be set conveniently.

High flexibility through individual expansion options

An expansion interface enables the connection of up to six IO modules. The modules and the order can be freely selected. The addressing of the expansion modules is performed automatically and the master module detects the plugged in module and the addressing. As extension options we provide currently a motor module, analog module, digital module or temperature module.

Rugged interfaces

The Phoenix clamps ensure a simple and extremely robust connection that makes the module in combination with the robust aluminium housing very durable and reliable.

Master module	
CAN	2× CAN acc. to ISO 11898 via RJ45 (2× socket)
Internal bus	Serial interface
Clamping technology	Pluggable phoenix clamp RM 3.5
Digital inputs	$16 \times$ DI, typically 0–24 V, max. 28.8 V; input current at rated voltage < 1–5 mA
Digital outputs	$16\times$ DO, typically 0–24 V, max. 28.8 V; 0.5 A maximum power per output; Protection against thermal overload
Analog inputs	2 contacts as reference-GND; 2 contacts for the analog inputs; Input voltage range: 0 V up to +10 V; Input current at +10 V: < 1 mA; Resolution: 10 bit
Analog outputs	2 contacts as reference-GND; 2 contacts for the analog outputs; Output voltage range: 0 V up to +10 V; Maximum output current 10 mA; Resolution: 10 bit
Dimensions (I×h)	180 mm × 120 mm
Temperature sensor	integrated
Storage temperature	−20°C up to +70°C
Operating temperature	0°C up to +60 $^{\circ}\text{C}$ (extended temperature range is optionally available)
Supply	24 V ±10 % – via 3-pole phoenix clamp
Supply IO	24 V ±10 % – via 3-pole phoenix clamp

Pin assignment



CAN RJ 45

2	CAN low	
3	CAN high	
4	CAN GND	
7	CANGND	



DIP switch baud rate

0	50	
1	125	
3	250	
4	500	
5	1000	



DIP switch module adress

imum 01 HEX	1
imum 7F HEX	127

Expansion modules	8DI/8DO	2H-bridge	PT100/PT1000	2AI/2AO	Relay module
DI 24 V	8	-	=	-	-
DO 24 V	8	+	+	+	+
AI 0-10 V	-	-	-	2	-
AO 0-10 V	-	+	-	2	-
PT 100/1000	-	-	2	-	-
Engine bridge 10 A	-	2	-	+	+
Potential-free contacts 6 A	-	-	-	-	4
CAN – adress settings	automatically				
CAN baud rate	over master module				
Power supply	24 V				

eControl PLC as a master with CODESYS V3

The PLCs of the eControl family are equipped with numerous communication interfaces, such as CAN, Ethernet, USB and serial interfaces. The PLCs have powerful CPUs which are optimized for the CODESYS target and web visualization. The robust and compact design in combination with CODESYS V3 as a development environment open up a variety of applications in industrial environments.

Order information

V965201110	Master module 16 DI/16 DO / 2 AI/2 AO 10 bit
V965201210	Module 2. 8 DI/8 DO
V965201310	Module 3. 2H bridge 10A
V965201410	Module 4.1. 2 PT 100/1000
V965201420	Module 4.2. 4 PT 100/1000
V965201510	Module 5. 2 AI/2 AO 10 bit
V965201610	Module 6. Relay module



Embedded-IO

The entire light series was designed for maximum cost savings at the same high performance. So far, it covers modules for signal processing of relays, temperature sensors and digital inputs and outputs. All the modules have an open and slim chassis design, which is clearly designed for the installation in the control cabinet.

Key Features



CANopen according to CiA Draft Standard DS 301 and DS 401



Short signal delay



Short circuit proof outputs



CAN baud rate up to 1 Mbit/s



Small dimensions



Simple top hat rail mounting

Interfaces

The modules are compact and they have comfortable design, which provides all the interfaces, LEDs and required switches on the front panel. Another feature is the integrated top hat rail mounting, which permits an easy mounting and dismounting.

LEDs and switches

The visualization of the status and current IO states successes via integrated LEDs for each IO. Configuring the module address and baud rate can be made easily and safely via DIP switches on the module. Thereby, a baud rate of up to 1 Mbit/s is adjustable according to CiA.

In- and outputs

The modules are available in partly configurable models with digital or analog inputs and outputs. They are galvanically isolated and short-circuit-proofed and guarantee a high reliability and resiliency. The wide input voltage range of 12 V DC to 30 V DC, open up wide areas of applications.

Signal processing

In addition to the inputs and outputs, the module has a powerful microcontroller, worked on the acquisition of the sensors, the control of actuators and the CAN protocol. Further, security mechanisms such as e.g. guarding are fully integrated into the remote IO.

CAN interface

The integrated CAN interface according to CANopen (DS 301 and 401) allows flexible use at different locations and positions in the production process. It is executed according to ISO 11898 and can be bridged. In this way, you can use several modules in series by looping through the CAN signals.

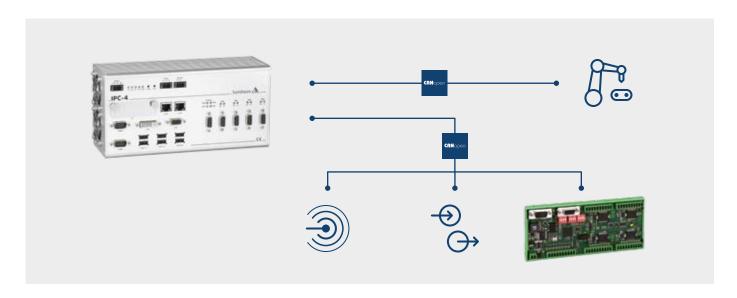
Combine the light modules with IPC-4 as a master in the CAN network

In its latest generation the IPC-4 combines the know-how of a system provider with the latest technology and is perfectly tailored for applications in the automation and automotive industry.

The new IPC with its scalable performance, clearly deposits itself from the competition. Computing power as well as the type and number of interfaces are offering immense possibilities for individual adjustment, for a maximum of flexibility. The housing is of course suitable for top hat rail mounting and allows an access to all ports on the front panel. This ensures a comfortable handling and avoids messy cabling.

Example of an automation application

IPC-4 is a master unit in the automation system and handles the control as well as the sensors and actors in a fieldbus network.



Module overview	DIO32-L	DIO32 8AI-L	AIO16-L	
CAN	1× CAN interface acc. to ISO 118	98, assignment acc. to DIN 41652, connection with D-	-Sub9 plug and socket (bridged)	
CAN protocol		DS 301 and 401		
Number of modules/bus	127			
Setting	of mo	dule address via 2 HEX switches, of baud rate via HEX	(switch	
Connection system	Clamping range 0.25 – 1.5 mm ² , solid wire			
Connection type	Spring connection			
Connection technology	Two-, three-wire connection, stripping length 10 mm		stripping length 10 mm	
Operating system display	1x LED green for operating mode (run) 1x LED red for error status (err) 32x LED green for set in- and outputs	1× LED green for operating mode (run) 1× LED red for error status (err) 1× LED green for supply voltage 32× LED green for set in- and outputs	1× LED green for operating mode (run) 1× LED red for error status (err) 1× LED green for supply voltage	
Dimensions (l×w×h)	147 mm × 77 mm × 37 mm	166 mm × 72 mm × 37 mm	147 mm × 77 mm × 37 mm	
Veight	155 g without clamps	102 g with	out clamps	
Type of installation		Top hat rail	·	
Storage temperature		−20°C up to +70°C		
Operating temperature	0°C up t	to +60 °C (extended temperature range is optionally a	availahlo)	
	o Cup t		uvunusit	
		90 % non-condensing		
Conformity EMC-requirements	121/25 . 201/25	EN 61000-6-4 and EN 61000-6-2 (Industrial sector)	124 V DC +20 0/-	
Power supply	12 V DC up to 30 V DC		nd 24 V DC ±20 %	
Current	30 mA 350 mA (all in- and outputs active, including LEDs)		mA uts active, including LEDs)	
Digital inputs	DIO32-L	DIO32 8AI-L	AIO16-L	
Number of inputs	16	0 – 32, configurable in 8-blocks	-	
witching level "1"	+8.0 V up to +30.0 V	+11.0 V up to +28.8 V	-	
switching level "0"	0.0 V up to +4.0 V	0.0 V up to +5.0 V	-	
Potential isolation	·	ve coupler	_	
nput current/input	3.0 / 6.5 mA	4 mA	_	
Sampling frequency	2.5 kHz	1 kHz		
Signal delay		00 μs	_	
Digital outputs	DI032-L	DIO32 8AI-L	AIO16-L	
Number of outputs	16	0 – 32, configurable in 8-blocks		
Circuit type		ide-Switch	_	
Potential isolation		ve coupler	_	
	VB – 0.85 V	VB – 0.16 V DC	_	
min. output voltage max. output current per			-	
thannel	600 mA	625 mA	-	
max. total output current	8 A	16 A	-	
Protective shutdown		overload protection	-	
Switching frequency		(Hz	-	
Free-wheeling diodes		uire external freewheel diodes	-	
Signal delay		00 μs	-	
Analog inputs	DIO32-L	DIO32 8AI-L	AIO16-L	
Number of inputs	-		8	
Resolution	-	12	bit	
Potential isolation	- Capacitive coupler		ve coupler	
nput voltage	 If required with assembly option: current input: 4 to 20 mA (not standard) 			
Samplerate	- 1 kHz		kHz	
Analog outputs	DIO32-L	DIO32 8AI-L	AIO16-L	
Number of outputs		-	8	
Resolution		-	12 bit	
Potential isolation		_	Capacitive coupler	
Output voltage		_	0 – 10 V DC	







Pin assignment DIO32-L



DIP switch module adress

Minimum 01 HEX	1
Maximum 7F HEX	127



DIP switch baud rate (in Kbit/s)

0	50
1	125
3	250
4	500
5	1000





CAN D-Sub9

1	-
2	CAN low
3	CAN GND
4	=
5	_
6	=
7	CAN high
8	_
9	-



Clamp block

1	E 1.0	Digital input / output 1.0
2	E 1.1	Digital input / output 1.1
3	E 1.2	Digital input / output 1.2
4	E 1.3	Digital input / output 1.3
5	E 1.4	Digital input / output 1.4
6	E 1.5	Digital input / output 1.5
7	E 1.6	Digital input / output 1.6
8	E 1.7	Digital input / output 1.7

Pin assignment DIO32-8AI-L, AIO16-L



DIP switch module adress

Minimum 01 HEX	1
Maximum 7F HEX	127



DIP switch baud rate (in Kbit/s)

0	50
1	125
3	250
4	500
5	1000





CAN D-Sub9

1	-
2	CAN low
3	CAN GND
4	=
5	=
6	=
7	CAN high
8	_
9	_

Order information

V965100000	DIO32-L
V965100100	DIO32 8AI-L
V930250210	DIO32 8AI-L (4× Spannungs- & 4× Stromeingänge)
V965100200	AIO16-L



TM-PT100/ 1000-L

Temperatures can easily be measured with the TM-PT100/1000-L with up to eight sensors. It contains possibilities for 4-wire and 2-wire technologie and thus provides a great amount of industrial-suitedness.

Key Features



CANopen according to CiA Draft Standard DS 301 and 401



CAN baud rate up to 1 Mbit/s



Small dimensions



Free choice of connection technology (4-wire/2-wire) and resistance sensors (PT100/PT1000)



Up to 8 measuring sensors per Module



Simple top hat rail mounting

Housing

The compact housing is made for being in a control cabinet. It contains a top hat rail mount and a front cover with all interfaces for better overview in the control cabinet. The technician will note the convenience while working at the bus cabling.

LEDs and switches

All inputs and outputs can be monitored with the help of LEDs. In addition to that, you can configure the baud rate of up to 1 Mbit/s and module address with DIP switches at the front cover. An additional DIP switch is meant for switching between 4-wire and 2-wire.

Measuring

The data is collected with four (4-wire) or eight (2-wire) sensors. You can choose between PT100 and PT1000 sensors and set the measurement speed to slow-mode with 100 ms or quick mode with 10 ms per channel and cycle.

CPU	16-bit microcontroller
CAN	1× CAN interface acc. to ISO 11898, galv. isolated, connection with D-Sub9 plug and socket (bridged), assignment acc. to DIN 41652
CAN protocol	DS 301 and 401
Number of modules/bus	127
Setting	of module address via 2 DIP switches of baud rate via DIP switch Resistance sensor selection via DIP switch Selection of the connection technology via DIP switch
Connection system	Rigid lines 0.20 – 1.50 mm ² Flexible lines 0.20 – 1.50 mm ²
Connection type	Spring connection and gold contacts
Connection technology	Optional 4-wire and/or 2-wire
Operating system display	1× LED green for operating mode (run) 1× LED red for error status (err) 1× LED green for VCC
Dimensions (l×w×h)	137 mm × 77 mm × 37 mm
Weight	140 g without clamps
Type of installation	Top hat rail
Storage temperature	−30 °C up to +70 °C
Operating temperature	0°C up to +60 $^{\circ}\text{C}$ (extended temperature range is optionally available)
Humidity	90 % non-condensing
Confirmity to EMC requirements	EN 61000-6-4 and EN 61000-6-2 (Industrial sector)
Supply voltage (VB)	12 V DC up to 30 V DC
Power consumption	30 mA
All in- and outputs active, including LEDs	350 mA

Pin assignment



DIP switch module adress

Minimum 01 HEX	1
Maximum 7F HEX	127



DIP switch baud rate (in Kbit/s)

	Strice in bada a race (iii rebie/5)
0	50
1	125
3	250
4	500
5	1000

CAN D-Sub9







Clamp block

1	E 1.0	Sensor 1
2	E 1.1	Sensor 2
3	E 1.2	Sensor 3
4	E 1.3	Sensor 4
5	E 1.4	Sensor 5
6	E 1.5	Sensor 6
7	E 1.6	Sensor 7
8	E 1.7	Sensor 8

Order information

V965101000 TM-PT100/1000-L

Signal processing

A STAR 12 microcontroller handles the sensors and the CAN protocol. TM-PT is also suited for control tasks via PWM/IO-interface.

CAN Interfaces

The integrated CAN interface is designed in accordance to DS 301 and 401 for a flexible use in different places and tasks in the CAN bus network. All Sontheim CAN interfaces comply to ISO 11898.



EC-DIO32

Digital 24 V module with 32 freely configurable in- and outputs and an EtherCAT and CAN interface.

Key Features



Signal delay with less than 400 µs



Safety features for high running safety



Easy access to all interfaces



Own intelligence for complex EtherCAT networks



Galv. isolated in- and outputs



Free configuration of in- and outputs



Analog and digital diagnostic functions



Compact aluminium housing with IP20 and integrated top hat rail mounting

Flexibility

The key to slim fieldbus networks as well as to efficient process automation is flexibility. The user has to be able to meet changing process requirements with existing products. The EC-DIO32 has been designed for these particular cases, where either the fieldbus system, the number or the kind of actors and sensors changes.

Freely configurable inputs and outputs

EC-DIO32 is a digital 24 V remote IO module, housing a 16-bit Motorola Freescale microprocessor and 32 freely configurable inputs and outputs. It is separated into four blocks of 8 interfaces each that can be configured and addressed via HEX-switches. Every block is galvanically isolated and has an own power supply. This enables the module to handle different voltages and allows the use in safety-relevant applications, e.g. guard doors.

Displays, switches and LEDs for a maximum of usability

LEDs and two 7-segment displays for each block show the status of the module channels. The network can therefore be created and monitored very easily.

Hardware	
CPU	16-bit microcontroller
Connection technology	Two-wire, three-wire connection
Operating system display	1× LED green for supply voltage (5 V) 1× LED green for operating mode (run) 1× LED red for error status (err) 32× LED green for set input/output
Dimensions (l×w×h)	241 mm × 120 mm × 48 mm
Weight	850 g
Protection class	IP20, EMC-requirements acc. to CE
Storage temperature	−30°C up to +70°C
Operating temperature	0 °C up to +60 °C
Humidity	90 % non-condensing
Power supply	24 V DC ±20 %
Total current (all in- and outputs active, including LEDs)	500 mA

Rugged	interfaces
--------	------------

3-point connection technology facilitates the direct connection of all sensors and actors with the module. The EC-DIO32 contains Phoenix clamps for easy and rugged conctact, making it robust and process proof in multiple applications.

EtherCAT and CAN interfaces

Many automation processes need a decentralized deployment of communication modules. That is why the EC-DIO32 has a 3-pole CAN interface and two RJ45 plugs for connecting different modules via Ethernet patch cable. In addition to that there is an automatic detection of CAN and EtherCAT network technology.

Diagnostic features via revertive monitoring

The device offers various possibilities for revertively monitoring power levels and switching habits. These features facilitate the detection of defect outputs. By monitoring the levels of input signals the module can also verify input faults. All the data is made available while running the EC-DIO32. It is also possible to implement a current measurement at the inputs and outputs for controlling absorption and delivery.

Digital inputs	
Number of inputs	Freely configurable in 8-blocks (max. 32)
Switching level "1"	+15.0 V up to +28.8 V
Switching level "0"	0.0 V up to +8.0 V
Potential isolation	Optocoupler
Input current/input	11 mA
Sampling frequency (Fg)	2.5 kHz
Signal delay	< 400 μs

Digital outputs	
Number of ouputs	Freely configurable in 8-blocks (max. 32)
Power	24 V DC ±20 %
Curcuit type	FET-Highside switch
Potential isolation	Optocoupler
Output current/output	1 A (short circuit proof)
Freewheel diodes	Yes, controlled inductors require external freewheel diodes
Signal delay	< 100 µs
Relay contact (when module active)	1× UM / 1 A
Switching level "1"	+15.0 V to +28.8 V DC

Pin assignment



RJ 45 Ethernet

1	LAN/EtherCAT_TX+
2	LAN/EtherCAT_TX-
3	LAN/EtherCAT_RX+
4	CAN L (low) (optional)
5	CAN H (high) (optional)
6	LAN/EtherCAT_RX-
7	CAN GND (ground) (optional)
-	



RJ 45

4 CAN L (low)
5 CAN H (high)
7 CAN GND





HEX-Switches module adress

Minimum 01 HEX	1
Maximum 7F HEX	127



HEX-Switch baud rate (in Kbit/s)

	•	•
0	10	
1	25	
2	50	
3	125	
4	250	
5	500	
6	800	
7	1000	

Order information

V966210000 EC-DIO32



EC-DIO32 RM35

Digital 24 V module with 32 freely configurable in- and outputs and an EtherCAT and CAN interface.

Key Features



Signal delay with less than 100 µs



Safety features for high running safety



Easy access to all interfaces



Own intelligence for complex EtherCAT networks



Galv. isolated in- and outputs



Free configuration of in- and outputs



Analog and digital diagnostic functions



Compact aluminium housing with IP20 and integrated top hat rail mounting

Flexibility

The key to lean fieldbus networks and efficient process automation lies in flexibility. The user has to be able to meet changing process requirements with existing products. The EC-DIO32 RM35 has been designed for these particular cases, where either the fieldbus system, the number or the kind of actors and sensors changes.

Freely configurable inputs and outputs

EC-DIO32 RM35 is a digital 24 V remote IO module, housing a 200 MHz NXP LPC with 32-bit and 32 freely configurable inputs and outputs. It is separated into four blocks of eight interfaces each that can be configured and addressed via two HEX-switches. Every block is galvanically isolated and has an own power supply. This enables the module to handle different voltages and allows the use in safety-relevant applications, e. g. guard doors.

Switches and LEDs for a maximum of usability

LEDs and switches for each block show the status of the module channels. The network can therefore be created and monitored very easily.

Hardware	
CPU	32-bit microcontroller
Connection technology	Two-wire-, three-wire connection
Operating system display	1× LED green for operating mode (Run) 1× LED rot for error (Err) 1× LED green mode CAN 1× LED green mode EtherCAT 4× LED Block configuration 32× LED green for set in- and outputs Fieldbus EtherCAT (LEDs on the RJ45 plug) 1× LED green transmit 1× LED orange EtherCAT status
Dimensions (l×w×h)	121 mm × 120 mm × 35 mm
Weight	approx. 400 g
Portection class	IP20, EMC-requirements according to CE
Storage temperature	-20°C up to +80°C
Operating temperature	−10 °C up to +60 °C
Humidity	90 % non-condensing
Power supply	24 V DC ±20 %
Current (all in- and outputs active, including LEDs)	500 mA

Digital inputs	
Number of inputs	Freely configurable in 8-blocks (max. 32)
Switching level "1"	+15.0 V up to +28.8 V DC (EN 61131-2, type 1)
Switching level "0"	0.0 V up to +5.0 V DC (EN 61131-2, type 1)
Input current/input	max. 5 mA
Input frequency (Fg)	5 kHz
Signal delay	< 100 μs

Digital outputs	
Number of outputs	Freely configurable in 8-blocks (max. 32)
Power supply	24 V DC ±20 %
Circuit type	Highside-Power switch
Output current/output	1 A (short circuit proof)
Freewheel diodes	Yes, controlled inductors require external freewheel diodes
Signal delay	< 100 μs
Switching level "1"	+15.0 V up to +28.8 V DC

Rugged interfaces

3-point connection technology facilitates the direct connection of all sensors and actors with the module. The EC-DIO32 RM35 contains Weidmüller clamps for easy and rugged conctact, making it robust and process proof in multiple applications.

EtherCAT and CAN interfaces

You can configure the module for a CANopen or EtherCAT network via a HEX switch. As interfaces for data exchange, it has two RJ45 ports and for CAN a D-Sub9 interface, allowing an easy connection with other modules.

Diagnostic features via revertive monitoring

The device offers various possibilities for revertively monitoring power levels and switching habits. These features facilitate the detection of defect outputs. By monitoring the levels of input signals the module can also verify input faults. All the data is made available while running the EC-DIO32 RM35.

Pin assignment



RJ 45 Ethernet

1	LAN/EtherCAT_TX+
2	LAN/EtherCAT_TX—
3	LAN/EtherCAT_RX+
4	=
5	-
6	LAN/EtherCAT_RX-
7	-
8	_





CAN D-Sub9

-			
2	CAN L (low)		
3	CAN GND		
7	(AN H (high)		





HEX-Switches module adress

1
127



HEX-Switch baud rate (in Kbit/s)

0	10
1	25
2	50
3	125
4	250
5	500
6	800
7	1000

Order information

V966213250 EC-DIO32 RM35



CAN-RS232 Interface-Converter

If you have occupied all serial interfaces, you can rely on the CAN-RS232 interface converter. It is a 24 V extension module for any desktop or industrial PC that provides another four RS232 channels according to CANopen with D-Sub9 plugs.

Key Features



Up to 4× RS232 interface with D-Sub9



CAN interface acc. to ISO 11898 with 3-pole phoenix clamp



Complies with the CANopen specification according to CiA



24 V DC supply with 3-pole phoenix clamp



Baud rate and module address configurable via HEX-switch



Status LED-display for module status, CAN and each RS232 channel with Rx-and Tx-display

Housing

The compact aluminium housing is made for being in a control cabinet. It contains a top hat rail mount and a front cover with all interfaces for better overview in the control cabinet. The technician will note the convenience while working at the bus cabling.

Signal processing

Besides its inputs and outputs the Interface Converter offers a powerful microcontroller that handles data acquisition of sensors, control of actors and the processing of any CAN data.

CAN interface

The integrated CAN interface is designed in accordance to DS 301 and DS401 for a flexible use in different places and tasks in the CAN bus network. All Sontheim CAN interfaces comply to ISO 11898.

CPU	16-bit microcontroller
CAN	1× CAN acc. to ISO 11898, galvanically isolated, assignment acc. to DIN 41652
COM interface	Connection via D-Sub9 plug
RS232 interface	Connection via D-Sub9 socket
Dimensions (l×w×h)	187 mm × 120 mm × 60 mm
Housing	Aluminium housing, Protection class IP20
Supply voltage	24 V DC via 3-pole phoenix clamp
Mounting rail	TS35
Operating temperature	0 °C up to +70 °C
Rel. Humidity	10 % up to 90 % non-condensing

Pin assignment



RS232

1	-
2	RxD
3	TxD
4	=
5	GND
6	=
7	=
8	=
9	_



CAN

1	CAN H (high)	
2	CAN L (low)	
3	CAN GND	



HEX-Switch baud rate (in Kbit/s)

0	10
1	25
2	50
3	125
4	250
5	500
6	1000

Order information

V930882000 CAN-RS232 Interface-Converter



RS422 Multiplexer

24 V module with a total of 10 inputs for incremental encorder.

Key Features



Total of 10 inputs for incremental encorder



24 V DC supply with 3-pole phoenix clamp



Compact housing for TS35 top hat rail mounting

Overview of all interfaces

All interfaces of the inputs and outputs are designed as RS422, the signals are accessible via D-Sub9 plugs and sockets.

Housing

The aluminium module is extremely compact and offers the possibility of top hat rail mounting. All interfaces are conveniently available on the front panel.

LEDs and switches

In addition to several LEDs for displaying the operating status, the multiplexer has two LEDs each to indicate the status of the respective input. A 9-pole and a 3-pole phoenix connector are used for signal distribution.

IOL

RS232 interface	Connection via D-Sub9 socket
Number of digital inputs	10
Number of digital outputs	1
Maximum baud rate	500 kHz
Dimensions (l×w×h)	241 mm × 120 mm × 48 mm
Housing	Aluminium housing, Protection class IP20
Supply voltage	24 V DC via 3-pole phoenix clamp
Mounting rail	TS35
Operating temperatur range	0 °C up to +70 °C
Rel. Humidity	10 % up to 90 % non-condensing
Rel. Humidity Switch data	10 % up to 90 % non-condensing
ŕ	10 % up to 90 % non-condensing
Switch data	
Switch data Power supply	5 V
Switch data Power supply Level Input	5V ±5V

8 mA



IGI 16

IGI16 is designed for capturing positioning data according to CiA specification for CAN networks. The device possesses the shortest conversion times and a high process reliability. That makes it the best choice for continuous operation in complex machine networks.

Key Features



16 incremental encorder inputs with up to 32 bit resolution



CAN interface with 4-pole phoenix clamp



24 V DC supply with 3-pole phoenix clamp



Baud rate and module address configurable via HEX switch



Complies with the CANopen specification according to CiA

Housing

The compact aluminium housing contains a top hat rail mount and a front cover with all interfaces for better overview in the control cabinet. The technician will note the convenience while working at the bus cabling.

Incremental encoder

Overall, the IGI has 16 incremental encoder interfaces. Five of them are directly connected to counters. The sixth can be switched to D3 to D13. Inc A and B possess a resolution of 32 bit. All others work with a standard 16 bit resolution. Each encoder uses an impulse quadruplication for 20,000 impulses at 5,000 steps per turn.

LEDs and switches

All inputs can be monitored with the help of LEDs at the clamps. In addition to that, you can configure the baud rate with a HEX switch at the front cover – easy and comfortable.

CPU	16-bit microcontroller
CAN	interface according to ISO 11898 galv. isolated Connection with 4-pole phoenix clamp or optionally with RJ45 plug
Connecton system	D-Sub9 plug
Setting	of baud rate via HEX switch
Dimensions (l×w×h)	241 mm × 120 mm × 48 mm
Weight	800 g
Protection class	IP20, EMC-requirements according to CE
Storage temperature	−30 °C up to +70 °C
Operating temperature	0°C up to +60°C
Humidity	90 % non-condensing
Power supply	24 V DC ±20 %

Inputs	
Number of inputs	16× for incremental encorder
Meter size	Inc A: 32 bit Inc B: 32 bit Inc C: 16 bit Inc D1: 16 bit Inc D2: 16 bit Inc D3 up to D13: 16 bit multiplexed
Fehlermodus	with watchdog error every 60 ms transmission of an error frame
Betriebszustandsanzeige	LEDs (red) for short circuit on Inc side LEDs (green) for multiplex-input RUN-LED (green) for identifier-reception ERROR-LED (red) for watchdogerror 24 V LED (green) for supply voltage

Pin assignment



CAN

1	CAN H (high)
2	CAN L (low)
3	CAN GND
Λ	Frdo



Incremental Encoder

1	GND
2	/B
3	GND
4	/A
5	24 V
6	24 V
7	GND
8	В
9	/A



HEX-Switch baud rate (in Kbit/s)

0	10
1	20
2	50
3	125
4	250
5	500
6	1000

Signal processing

Besides its inputs the IGI16 offers a powerful microcontroller that handles the data acquisition of sensors and the processing of any CAN data.

CAN interface

The integrated CAN interface is designed in accordance to DS 301 and 401 for a flexible use in different places and tasks in the CAN bus network. All Sontheim CAN interfaces comply to ISO 11898.

Order information

V96630200 IGI – Incremental Encoder Interface 16 channel



Relay module

The relay module allows the control of up to eight heating cartridges with 400 V. It is designed in the open construction typical for the Light family and impresses with its very good price-performance ratio. With its extremely short conversion times for signal processing and high process reliability, this module is also ideally suited for continuous operation in complex machine networks.

Key Features



Controlling up to 8 heating cartridges



Integrated safety functions



Small dimensions



Simple top hat rail mounting

Housing

The compact housing is made for being in a control cabinet. It contains a top hat rail mount and a front cover with all interfaces for better overview in the control cabinet. The technician will note the convenience while working at the bus cabling.

Power supply

Phase L1 is only looped in. L2 and L3 are used for controlling the consumers. There is a current measurement integrated that enables a monitoring of each relay. It is build in two blocks with four relay each.

Relay

A key feature of the relay module is its high process reliability. Its RP1 is a semiconductor relay for embedded board assembly with three regulated control currents for handling its consumers. Major advantages are both a high surge current and interference resistivity while switching AC loads.

CPU	ARM 7-based		
CAN	1× CAN interface according to ISO 11898, Connection with RJ45 socket		
Operating system display	1× LED green for operating mode (run) 1× LED red for error status (err) 1× LED green for power supply		
Setting	of module address via 2 HEX switches of baud rate via solder jumper		
Dimensions (l×w×h)	285 mm × 77 mm × 37 mm		
Weight	185 g with clamps 155 g without clamps		
Type of installation	Hat rail		
Storage temperature	−30 °C up to +70 °C		
Operating temperature	0°C up to +60 $^{\circ}\text{C}$ (extended temperature range is optionally available)		
Humidity	90 % non-condensing		
Conformity for EMC directives	EN 61000-6-4 and EN 61000-6-2 (Industrial sector)		
Power supply	12 V DC up to 30 V DC		

Relay-Data	
Load voltage range	2-530 V AC
Peak reverse voltage	1000 V
Input – load circuit	4 kV AC
Nominal frequency range	45 – 65 Hz
Power factor	> 0.5
Switch-on zero voltage	< 10 V
Approvals	UL, cUL, VDE
CE-Identification	Yes

LEDs and switches

Several status LEDs allow to visualize different operating modes and warning messages from its safety functions like heartbeat telegrams. Configuration of the module address and baud rate can be done via HEX switches and solder jumpers. It is turned to 250 Kbit/s as a standard.

Signal processing

There is a powerful ARM7 microcontroller on the module for controlling the relay and the CAN protocol. Additionally, heartbeat is integrated into the device.

Pin assignment



RJ 45				
	1	-		
	2	_		
	3	-		
	4	CAN L (low)		
	5	CAN H (high)		
	6	=		
	7	CAN GND (ground)		
	8	_		

CAN interface

The integrated CAN interface is designed in accordance to DS 301 and 401 for a flexible use in different places and tasks in the CAN bus network. All Sontheim CAN interfaces comply to ISO 11898.

Order information

V966305100 RM-Relay module



mSiEcomTCtt

mSiEcomTCtt extends the Sontheim product portfolio with an extremely compact Computer-on-Module. It has an Intel Atom processor and various interfaces. Thanks to the extended temperature range of –40 °C to +85 °C, the module is also ideal for the use in harsh environments.

Key Features



COM Express mini, Type 10



Intel Atom E6xx (600 MHz, 1 GHz, 1.3 GHz and 1.6 GHz)



Onboard 10/100/1000 Mbit LAN



1× CAN interface acc. to ISO 11898



6× USB 2.0



3× PCI Express



Also suitable for harsh environments due to increased temperature range

Variety of interfaces and scalable performance

Beside six USB 2.0 interfaces, the mSiEcomTCtt has one CAN channel. Furthermore, Ethernet and also I²C for controlling peripheral components are integrated. The chip sets are ranging currently from 600 MHz up to 1.6 GHz with an Intel Atom. Depending on the requirements up to 2 GB DDR2-800 RAM can be used, thereby also intensive tasks are possible with low power consumption.

Compact form factor

Due to the compact design (COM Express mini, Type 10), the mSiecomTCtt can be mounted as a piggy-back variant onto another PCB and is ideally suited for the development of small devices, profitting from the high degree of standardization and scalability of the COM Express standard. Especially for mobile embedded handheld systems as well as for small portable, stationary and in-vehicle devices that are used in various application areas, the mSiEcomTCtt is the perfect solution.

CPU	Intel Atom E6xx (600 MHz, 1 GHz, 1.3 GHz and 1.6 GHz)		
Cache	512 KB L2 Cache		
Chipset	Intel Plattform Controller Hub EG20T		
RAM	up to 2 GB DDR2-800 RAM		
CAN interface	1x CAN 2.0 B active, up to 1 Mbit/s		
USB	6× USB 2.0		
Ethernet	10/100/1000 Mbit LAN		
Interface	GPIO on COM Express Connector		
SPI/SM Bus Support	External Boot via SPI flash device / SM Bus Support yes		
PCI Express	3x PCle		
SATA II	2x		
UART	1x		
Audio controller	Intel® High Definition Audio		
Graphic controller	integrated 2D/3D Graphics Engine, Gfx Core 333/400 MHz, shared VRAM Video Encode: MPEG4, H.263, H.264 Video Decode: MPEG2, MPEG4, VC1, WMV9, H.264		
Resolution	LVDS 18/24 bit 1280×768 @60 Hz SDVO 1280×1024 @85 Hz		
Operating system	Windows XP, XP embedded, 7, embedded 7, Linux		
Dimensions (l×w)	55 mm × 84 mm, COM Express mini, Type 10		
Storage temperature	-30°C up to $+85^{\circ}\text{C}$, extended -40°C up to $+85^{\circ}\text{C}$		
Operating temperature	0°C up to +60 $^{\circ}\text{C}$, extended –40 $^{\circ}\text{C}$ up to +85 $^{\circ}\text{C}$		
Rel. humidity	Operating: 10 % up to 90 %, Storage: 5 % up to 95 % non-condensing		
Power supply	5.2-5.8 Watt @5 V		





Designed for commercial and industrial temperature range

In addition to the normal temperature range the module is also suitable for the extended industrial temperature range (E2) from $-40\,^{\circ}$ C to $+85\,^{\circ}$ C. This opens a wide range of applications in the automotive-, automation-, medical technology, and in other work environments which are not matching the commercial temperature range.

mSiEcomTCtt and our embedded PC – a reliable combination

You are looking for the appropriate embedded platform for your automation application. Combine mSiEcomTCtt with our ePC and benefit from our know-how and the full service from the expert

- Variety of interfaces (modular design)
- IP20 metal housing for a high EMC protection
- Use as a PLC, CAN bus master or slave, signal processing center and much more.
- Suitable for industrial use
- · Passive cooling

Order information

V970005000 mSiEcomTCtt



i.MX 6

The ultra-energy-saving Computer-on-Module offers an optimal price performance ratio. Scalable building blocks facilitate customized mobile and cross-linked embedded solutions based on ARM technology.

Key Features



Freescale i.MX6 (Single, Dual, Quad Core, 800 MHz up to 1.2 GHz)



Up to 4 GB DDR3 memory



Onboard 10/100/1000 Mbit LAN



Numerous interfaces, e.g. 3× USB 2.0, 3× PCIe



Extended temperature range



Evaluation board on-demand

Scalable performance and compact form factor

The i.MX 6 board from Sontheim is based on a 314-pin MXM 3.0 connector and a size of 82 mm \times 50 mm. This creates extremely compact, durable and cost-effective development potentialities for mobile embedded handheld systems as well as little portable, stationary and in-vehicle devices that can be used in various application fields.

Designed for commercial and industrial temperature range

Beside the standard, the i.MX 6 board is ruggedized for an extended industrial temperature range from –40 °C up to +85 °C. This leads to various applications in the automotive sector, in automation, medical technology and further work environments that don't correlate the commercial temperature range and involve harsh environmental conditions. Furthermore, an evaluation board is available on request.

СРИ	Freescale i.MX6 Single, Dual and Quad Core ARM Cortex-A9 800 MHz, 1 GHz and 1.2 GHz		
Graphic	Dual Display HD 1080p encoded and decoded 2D and 3D Speed-up		
RAM	DDR2 or DDR3 up to 4 GB		
Memory	up to 64 GB NAND/eMMC on-module (customized)		
USB	3× USB 2.0		
Ethernet	10/100/1000 Mbit LAN		
Display	Parallel LCD 18/24 bit LVDS single channel 18/24 bit HDMI		
Image Capture Interface	2 interfaces (PCAM, CSI)		
Serial interfaces	2× RX/TX (Ser 1/3); 2× UART (Ser 0/2)		
Further interfaces	up to 3× PCIe, MLB150, 12× GPIOs, SDIO, SATA eMMC, 2× SPI, $5 \times l^2 C$, $2 \times l^2 S$, SPDIF WDT, 2× CAN, battery and system management		
Operating system support	Linux Windows embedded compact 7 (on request) Android (on request)		
Operating temperature	0°C up to +60 $^{\circ}\text{C}$, extended range: –40 $^{\circ}\text{C}$ up to +85 $^{\circ}\text{C}$		
Dimensions	SMARC standard: 82 mm × 50 mm		





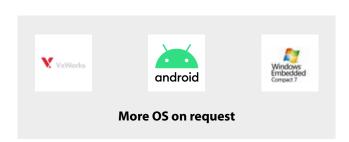
IO features of the 314-pin MXM 3.0 connector



Evaluation board



Supported operating systems





i.MX8

The i.MX 8 family offers an optimal price-performance ratio. Scalable building blocks enable customized embedded solutions based on ARM® technology. Thanks to an integrated neural processing unit, the i.MX 8 offers the best conditions for AI and ML applications and is optimized for telemetry applications.

Key Features



Freescale i.MX 8 (Dual Core, Quad Core, 1.2 GHz – 1.8 GHz)



Up to 8 GB DDR4 memory



On-Board 10/100/1000 Mbit LAN



Variety of interfaces, e.g. 3× USB 2.0, 3× PCIe



CAN and CAN FD



Extended temperature range



Optimized for AI and ML applications



Optimized for telemetry applications



Evaluation board on-demand

Scalable performance and compact form factor

The i.MX 8 board from Sontheim is based on a 314-pin MXM 3.0 connector with standard dimensions of 82 mm × 50 mm. This creates extremely compact, durable and cost-effective development options for mobile embedded handheld systems as well as small portable, stationary and in-vehicle devices that can be used in a wide range of application areas. The i.MX 8 is available in two variants. The i.MX 8M Plus variant for high performance applications, optimized for Al and ML applications and the i.MX 8X Lite variant for high performance telemetry and industrial applications. The i.MX 8X Lite variant has been specially optimized and developed for the Sontheim telemetry series COMhawk® xt.

Designed for commercial and industrial temperature range

In addition to the normal temperature range, the i.MX 8 board is also designed for the extended industrial temperature range of $-40\,^{\circ}\text{C}$ to $+105\,^{\circ}\text{C}$ – the i.MX 8X Lite variant even up to $+125\,^{\circ}\text{C}$ (AEC-Q100 Grade 2 device). This opens up a wide range of applications in the automotive sector, in automation, in medical technology and in other working environments that do not correspond to the commercial temperature range and involve harsh environmental conditions. In addition, an evaluation board is already available on request.

Overview of the target applications

Industrial:

Control systems, architectures with time-critical networking, Ethernet or CAN networks, HMIs and IPCs, robot controllers, printing systems, industrial handheld devices, intelligent industrial cameras and much more.

Automotive

High-performance telemetry and vehicle gateways, camera systems, vehicle interfaces (VCIs), ECUs, data loggers with analysis (AI), joysticks, displays and much more.

Optimized for machine learning and Al applications

The i.MX 8 board from Sontheim features an integrated neural processing unit (NPU) that delivers up to 2.3 TOPS (Tera Operations Per Second). This gives the board a processor that is used exclusively for machine learning and enables compute-intensive Al applications. As a result, the ML/Kl application no longer needs to be moved to the cloud, but can run directly on the i.MX 8 processor – personal user data is also better protected as a result. Applications such as the recognition of multiple complex neural networks, human poses and emotions, or the monitoring of multiple objects are thus possible.

Technical data

	i.MX 8M Plus	i.MX 8X Lite	
CPU	Freescale i.MX 8 Quad Core ARM Cortex-A53 1.8 GHz	Freescale i.MX 8 Dual Core ARM Cortex-A35 1.2 GHz	
MCU	Freescale Cortex-M7 800 MHz	Freescale Cortex-M4F 170 MHz	
RAM	up to 8 GB 132-bit DDR4	up to 1 GB 16-bit LPDDR4	
GPU	GC7000UL (2 shaders), OpenGL ES 1.1/2.0/3.0/3.1, OpenVG 1.1, Vulkan, OpenCL 1.2; GC520L (2D)	-	
NAND Flash	up to 64 GB eMMC (on-module)	up to 8 GB eMMC (on-module)	
Security	CAAM, RDC, Trust Zone	Trust Zone	
AI/ML	Neural Processing Unit 2.3 TOPS	-	
Camera	2× MIPI CSI (4-lanes each) 2× ISP up to 12 MP resolution	-	
Display	HDMI 2.0a Tx, MIPI DSI (4-lanes) LVDS (4/8-lanes)	1× Parallel Display	
Video Decode Video Encode	1080p60 HEVC, H.264, VP9, VP8 1080p60 H.265, H.264	-	
Audio	18× I2S TDM (32 b @ 384 kHz), ASRC, 8-ch. PDM DMIC input, eARC	-	
Interfaces	2× GbE (1× TSN), 2× CAN/CAN FD 3× SD/eMMC, Raw NAND 2× USB 3.0/ 2.0 5× UART, 6× I ² C, 3× SPI, 1× PCIe 3.0	2× GbE (1× TSN), 3× CAN/CAN FD 3× SD/eMMC, Raw NAND 2× USB 2.0 4× UART, 3× I ² C, 3× SPI, 1× PCIe 3.0	
Package	LFBGA-548	BGA-388	
Operating system support	Linux	Linux	
Operating temperature	0°C up to +95 $^{\circ}\text{C}$, extended range: -40°C up to +105 $^{\circ}\text{C}$	-40°C up to $+105^{\circ}\text{C}$, extended range: -40°C up to $+125^{\circ}\text{C}$	
Dimensions	SMARC Standard: 82 mm × 50 mm	SMARC Standard: 82 mm × 50 mm	







SMC100

SMC100 is a stepper motion controller for bipolar 2-phase stepper motors. Similar to MC105 the controller offers some functions for configuration and safety. You will benefit from an integrated logic module for configuring and saving operating data.

Key Features



Control of two bipolar 2-phase stepper motors



Phase current of up to 10 A



Four galvanically isolated in-and outputs



1× CAN interface acc. to ISO 11898



Own intelligence for self regulation and data management



Free configuration and storage operating data



Compact housing with IP20 and integrated top hat rail mounting

Housing

The compact housing is made of aluminium. It contains a top hat rail mount and a front cover with all interfaces for better overview in the control cabinet. The technician will note the convenience while working at the bus cabling. You can also set module address and baud rate in short time via DIP switch.

Stepper motor

All connected stepper motors are current-controlled. Either 24 V or 48 V stepper motors with up to 10 A can be dealt with. The current in each phase is seperately controlled. Finally, standby current can be adjusted to the nominal current between 0 and 100 %.

CPU	Texas Instruments TMS320 DSP		
Fieldbus	CANopen acc. to DS 402		
Interfaces	$4 \times$ DI / $4 \times$ DO, galv. isolated, optional $1 \times$ encoder interface		
Operating modes	1/1, 1/2, microstep		
Operating system display	1× LED green for supply voltage (5 V) 1× LED green for operating mode (run) 1× LED red for error status (err)		
Dimensions (l×w×h)	115 mm × 45 mm × 118 mm		
Housing	Aluminium housing with protection class IP20		
Storage temperature	–10 °C up to +70 °C		
Operating temperature	0°C up to +60°C		
Rel. humidity	90% non-condensing		
Power supply	24 V DC / 48 V DC		
Supply of the motors	isolated, 24 V / 48 V DC up to max. 10 A		

Operation modes

You can switch between full, half and micro-step. There is an incremental encoder with a resolution of 16 bit available as well.

Safety first

The current limit can be configured and saved as a basis value, avoiding errors in the calculation. Like all our controlling devices SMC100 also contains an emergencystop function which is activated as soon as it registers a lack of bus communication.

Pin assignment





CAN D-Sub9

1	-
2	CAN low
3	CAN GND
4	=
5	-
6	=
7	CAN high
8	=
0	_



DIP switch

0	10		
1	20		
2	50		
3	125		
4	250		
5	500		
6	800		
7	1000		





Order information

V966295400

SMC100



MC105

MC105 is a motion controller for up to four DC motors. It has various configuration options and security functions for extremely high ease of use. An integrated logic module automatically sets and saves all relevant operation data. The motors are all current controlled. It is possible to handle 24 V DC motors with up to 5 A via incremental encoder with a resolution of up to 12 bit.

Key Features



Own intelligence for self regulation and data management



Safety features for high operating safety



Free configuration and storage of operating data



Compact housing with IP20 and integrated top hat rail mounting

Functions of the channel

One motor can be controlled per channel. One encoder and one power supply per channel are available. Current limitation and current measurement can also be performed individually

Safety is a top priority

The limit current is definable and is stored by the module as a base value, thus avoiding errors in the current calculation. The MC105 additionally has an emergency stop function, which is triggered in the absence of bus communication.

CPU	Philips Arm 7
Fieldbus	EtherCAT
LEDs	1× LED green for power supply 1× LED green for operation mode (Run) 1× LED red for error (Err)
Display	2 lines à 16 signs
Dimensions (l×w×h)	241 mm × 120 mm × 48 mm
Weight	approx. 800 g
Housing	Aluminium housing wit protection class IP20
Storage temperature	−10 °C up to +70 °C
Operating temperature	0°C up to +60°C
Rel. humidity	90 % non-condensing
•	•
Supply of the motors	isolated, 24 V DC up to max. 5 A

Pin assignment





RJ 45

1	TX+
2	TX-
3	RX+
4	=
5	-
6	RX-
7	-
8	=

9-pole phoenix connection

1	24 V (supply)	
2	0 V (supply)	
3	24 V (Encoder)	
4	0 V (Encoder)	
5	A (Encoder)	
6	B (Encoder)	
7	0 V (Encoder)	
8	+ (Motor)	
9	- (Motor)	

Order information

V966295000 MC105-4 EtherCAT



EvoPrint®

Our future-oriented product portfolio allows the integration of the EvoPrint® printing system into existing processes without any difficulties. This includes digital and analog IO modules, hydraulic valve controls, drive technologies, PLCs and scalable industrial PCs with integrated fieldbus interfaces.

Key Features



Printing during positive or negative acceleration



Active speed compensation



Software and firmware updates in the field via LAN



HP Inkjet Technology



Robust aluminium housing

The request

Are you looking for an industrial printing system that can be quickly, easily and fully integrated into your production processes? Do you want professional printing results, regardless of the materials used and the printing speed?

The situation

Most suppliers of HP Inkjet Technology printing systems are offering solutions, that are extremely difficult to integrate into existing production processes. They often require a separate space between two steps and additional time for the printing. Moreover, there are only few possibilities to integrate controls and the user interface into existing control systems. Common systems are sold with an extra PC-based interface – which requires room, money and specially trained operators!



The elegant solution

EvoPrint® provides seamless integration of an industrial printing system into an existing machine without changing the production line. With a maximum print speed of up to 180 m/min or 3 m/s at 300 dpi resolution, EvoPrint® is thus considerably faster than conventional printing systems. Even during acceleration, precise printing is still possible. Furthermore, active speed compensation avoids rupture and warp, while the direction detection eliminates double printing. You will save process time and material costs! EvoPrint® offers software tools, which can be fully integrated into existing customer interfaces without the need for an extra PC-based interface in the machine. The printing system itself is connected by standard LAN/Ethernet for image transfer. The control can be done by fieldbus like EtherCAT or CAN as well as LAN or incremental encoders.

Application areas

EvoPrint® is tested and approved in practice. Due to the close cooperation with our customers in combination with our outstanding know-how as a system integrator, we provide individually tailored system solutions for various branches of industry:

Wide area of expandabilities

- · Performance resources even at complex applications
- 32-bit microprocessor with 200 MHz
- · 64 MB RAM and 32 MB Flash on board

Customizable applications

- · No change of production line
- · Assembly at static or moving axes
- Printing of text, 1D & 2D barcodes and images

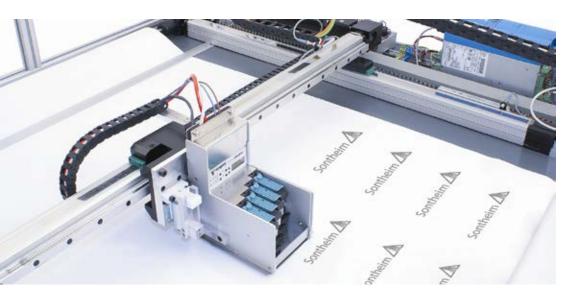
Highest quality

- 300 dpi at a printing speed of 180 m/min
- · Active velocity compensation
- Course detection
- · Based on HP Inkjet Technology

Future-proof due to innovative technology

- EtherCAT and CAN, standard-ethernet and incremental encoder
- Software tools for integration into existing application software

CPU	Powerful 32-bit microcontroller with 200 MHz clock frequency Fast FPGA to control the cartridges
Storage	32 MB Flash, 64 MB RAM on board
Connections	1× RJ45 LAN 100 Mbit IEEE 802.3 2× RJ45 (EtherCAT or CAN), 2× Incremental (Encoder) Interface (D-Sub9) 1× Supply voltage 9-pole phoenix 4× Digital outputs (Ub –0.5 V) 1× RS232 (D-Sub9)
Control panel/membrane keyboard	4 navigation keys for menu operation, 6× status LEDs for EtherCAT/CAN and LAN
LCD	$LCD\ display\ with\ 2\times8\ characters\ for\ device\ status, error\ code\ display, filling\ level\ alarm$
Speed	Maximum print speed up to 180 m/min at 300 dpi resolution
Print distance	< 2 mm
Print height	max. 5 cm in one print process
Installation options	Static or moving axes
Number of cartridges	4× HP Inkjet Technology
Supported cartridges	C8842A versatile black, Q2344A SPS1918 DYE Black C6168A, C6169A, C6170A and C6173A Spot Color (red, green, blue and yellow) VP90-E (UV curing), others on request
Average droplet size	26–29 pl (depending on the ink used)
Bulk system management	Supply via 1 of 2 bulk tanks for continuous printing of large jobs
Cartridge management	Cartridge calibration (pre-warming, spitting, pulse width, voltage)
Software	Various software tools for configuration and integration into existing applications Easily programmable 32-bit API (DLL)
Features	Printing during positive or negative acceleration Active speed compensation (no warping or tearing of the printed image!) Direction detection (positive, negative) Software/Firmware Update in the field via LAN Dust protected
Dimensions (l×w×h)	187 mm × 114 mm × 218 mm
Protection class housing	IP52
Weight	approx. 3.3 kg
Rel. humidity during printing	10 % – 80 % non-condensing
Rel. storage humidity	10 % – 80 % non-condensing
	1095
Operating temperature during printing	+10°C up to +40°C
Operating temperature during printing Storage temperature	+10°C up to +30°C



Sample application: EvoPrint® in motion. Assembled at a moving axis on a xy-plottertable.



Production

The Sontheim company has been producing the broad portfolio in-house since its foundation and thus has full control over quality and production processes. We cover the entire product life cycle, including the design and development phase, production, and integration and support. This contributes to very close customer support and enables fast and agile responses. The range of services includes individual prototypes, series deliveries and customized solutions.



Diagnostics

Visualization and Monitoring







MDT® 2.0

The Modular Diagnostic Tool 2.0 offers an OPC UA server and client in addition to ODX and OTX standard. This ensures comprehensive and simple operability, which is additionally supported by Visual Studio®.

Key Features



OPC UA server & client



ODX acc. to ISO 22901-1



OTX acc. to ISO 13209



Multi platform support



High-performance runtime system

Innovative machine park monitoring – based on standards

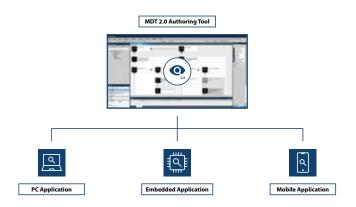
The new MDT® 2.0 is a standardized tool to access data of the machines. It enables the standardization of the data description (ODX), the programming (OTX) and the sharing & provision of the data (OPC UA). With the MDT® 2.0 tool chain, you have various options for creating, structuring and implementing test bench workflows, based on the industry standard OTX (Open Test Sequence eXchange format) according to ISO 13209, while the ODX 2.2.0 standard (Open Diagnostic Data Exchange) guarantees reusability of test bench services. Thanks to the platform-independent OPC UA architecture, the information obtained can be transmitted to a supervisor and thus integrated in the entire environment.

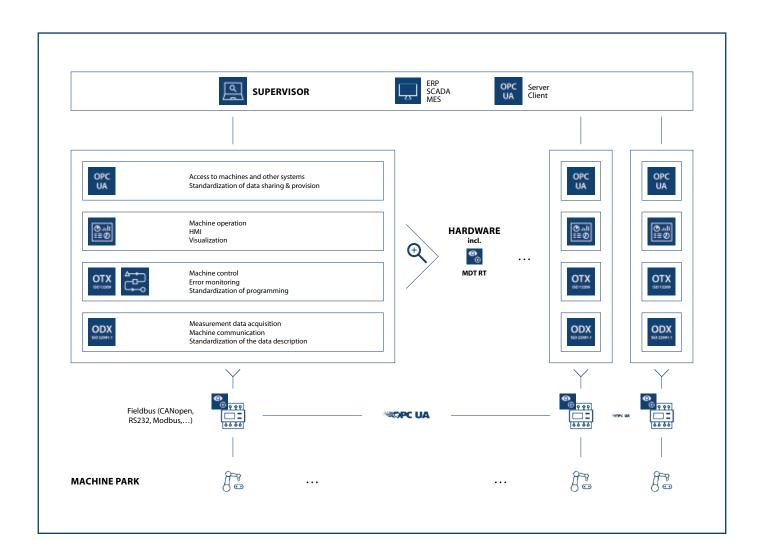
Multiplatform support – one workflow for all end-use applications

The extremely lean runtime system is designed specifically for multi-platform applications and provides GUI support as well as a platform-independent description of the runtime workflow language. This reduces both implementation and testing efforts for your applications across multiple PC, mobile or embedded platforms. In doing so, the MDT® 2.0 allows you to create your test bench control once and run it on a wide variety of environments such as Windows, Linux x86, Linux ARM or QNX without any customizations.

Modern design and new graphic modules

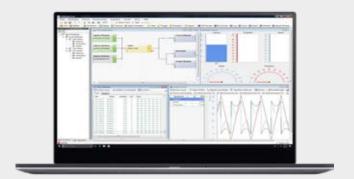
A new, clean and modern design allows the use of Visual Studio plug-ins, for example for SVN or Git. New graphical elements such as 2D and 3D animations can be used to create your diagnostic application. The diagnostics are thus more visually appealing and the intuitive usability for the service personnel and the diagnostic user is once again significantly increased..





Order information

V940800300	MDT® 2.0 Authoring system
C940800300	MDT® 2.0 Authoring system maintenance



CANexplorer 4

Modular, intuitive, efficient – CANexplorer 4 is a completely new developed field bus-analyzing software which represents the huge know-how in working with CAN networks in complex machines and vehicles. The new generation obtains a significantly enhanced range of functions and an improved handling. This makes the CANexplorer 4 a very intuitive and powerful tool.

Key Features



User-defined measurements setups with graphic elements and Drag and Drop



Receive, edit, transmit and abstract raw data



J1939-protocol support



CANopen-protocol support



Modular design with expansion options



Import and export from signal databases

Data processing

CANexplorer 4 offers various functions for processing CAN data, e.g. classical text-based traces, graphs, bar graphs, LEDs, filters and triggers. Generating a test set-up can be carried out by connecting different functional elements via Drag and Drop. This enables the software to consequently display complex processes in a visual and common manner.

Visualization

You can adapt the data visualization by defining triggers and filters. It is also possible to take an active part in the bus communication and generate and transmit messages that are also shown in a visualization. Have your telegrams sent manually, fully automatic or via trigger.

Data abstraction

Use an integrated protocol abstraction for automatically interpreting data to CANopen and J1939. The CAN data is then available as pre-processed and readable information. Further protocol stacks can easily be added with updates. All proprietary protocols and RawCAN data can be processed with a manual symbol editor. This tool is used for defining symbols and translating the payload of a CAN frame into comprehensible values.

Parallel processes

CANexplorer 4 obtains a multi-thread support for parallel usage next to other applications running on a PC and the visualization of various modules at the same time.

Overview of the most important modules:

Input:

CAN explorer 4 obtains various possibilities for manually or automatically creating CAN data as well as reading CAN messages at the bus.

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Signal generator Creation of signal processes.

Transmit Fast access to pre-defined CAN messages.



Replay Replay Replay of previously recorded CAN log-data for an analysis of the CAN bus data.

It is possible to apply original time-settings of the records.



Receiving and transmitting of CAN data. All Sontheim interfaces are supported,

e. g. CANUSB, CANUSBlight and PowerCAN.

Processing:

Different filters provide a comfortable handling of the various CAN data. Moreover, the user can abstract the data to J1939 and CANopen.



Filter One can use filters for CAN identifier, areas of CAN identifier, data bytes and

message types. The filters have a positive and a negative output.



Protocol Filter

The integrated filters J1939 and CANopen offer an abstraction and

pre-processing of CAN bus data traffic.



Trigger

Creation of an event which can start a pre-defined operation. The user can choose

between different triggers (e. g. data bytes of data bits) for a maximum of flexibility.

Visualization And Recording:

The modular-based design of the CANexplorer provides individual adaptation of the visualization and the display of specifically required data. The CAN bus traffic can be recorded and visualized easily via different elements. Of course, the various instruments can be chosen and configured according to the user's requirements.



Log Module Easy writing of CAN messages into a log-file.



Trace Tabular display of CAN messages in the static or trace mode.

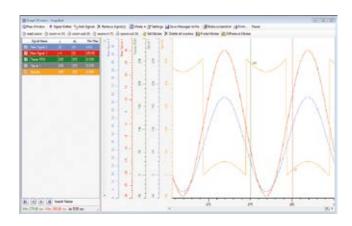


Graph Visualization of signals via graphs. Underlining events via placing of markers.



Signal Monitor Symbol Editor Bar-Graph Statistic Display of signals in a table, including minimum and maximum. Definition of symbols down to the Bit layer for a simplified and more lucid illustration of CAN information. Visualization of signals via bar-graphs or tachometer. Indication of bus statistics (e.g. amount of received / transmitted messages, bus-charge and others).

Operating system	Windows 2000 SP4, XP, Vista (32-Bit), 7, 8, 10
CPU	1.6 GHz Intel Pentium
RAM	512 MB
Graphics	1024×768 px, 16 mio. colors
Minimum hard disk space	min. 80 MB
Supported CAN Hardware	COMfalcon® CANUSB CANFOX® CANUSBlight PowerCAN-PCI V1 and V2 PowerCAN-PC104+ PowerCAN-PC1104 V2 Other CAN hardware available upon enquiry



Features	
Receiving and transmitting CAN messages	Signal generator with different signals (sinus, saw tooth, rectangle) Manual transmitting of definable CAN messages Cyclic transmitting of definable CAN messages Transmitting in block mode
Filter	CAN explorer 4 supports filtering for identifier, data bytes, symbols and message types
Trigger	Canexplorer 4 uses pre- and post-trigger
Signal datenbase	Saving of messages in a database as well as visualization via texts and graphic elements for intuitive handling Editor for generating and processing of signals (message, multiplexer, key, groups and signal) For both data import and export there are various data types supported
Visualization	Trace, graph, bar-graph, tachometer, symbol-monitor
Data processing	Writing in log-file, replay mode
Protocol support	RawCAN, CANopen, J1939, implementation of proprietary protocols upon enquiry
Bus statistic	Overview of transmitted and received messages bus-charge and CAN levels
Quick Trace	Quick monitoring of the CAN channels without previous creation of a test setup

Order information

V940340010	CANexplorer 4 Basis
V940340099	Software maintenance
V940340020	Extended graph
V940340021	Extended measurement setup
V940340022	BarGraph & Tacho, LED
V940340023	Protocol filter J1939
V940340024	Protocol filter CANopen
V940340025	Signal-generator
V940340026	DBC-import & export
V940340027	ASC-support
V940340029	Vector-support for CANcardXL
V940340030	Peak-support for PCAN-USB



Custom Developements

As an expert in various fieldbus technologies, we would be happy to support you with customer-specific developments in the area of software, hardware, firmware, as well as the design and conception of your automation or automotive solution. Here you benefit from our holistic know-how as a system provider and the perfect interaction of functional hardware and suitable firmware up to the modular and optimized software.



Connectivity

IoT-Gateways, Interfaces, Cloud Software







eSys-IDC4E1

eSys-IDC4E1 enables the connection of different CAN buses via IP networks. The high-performance CAN-to-Ethernet gateway provides a LAN connection and four galvanically isolated CAN interfaces. In addition, the module provides various measurement and diagnostic functions in machine fieldbus systems.

Key Features

32 bit

Powerful 32-bit CPU



1× Ethernet, 10/100 Mbit/s



4× CAN acc. to ISO 11898, galv. isolated



Active resistance measurement



Integrated error frame detection



Robust aluminium housing



Including standardized SAE J2534 interface

CAN-to-Ethernet gateway with integrated diagnostic functions

In addition to four galvanically isolated CAN channels eSys-IDC4E1 provides an Ethernet connection for the transmission of data to a higher-level computer. For CAN bus monitoring an active resistance measurement and an error frame detection is implemented. This feature allows surveillance and monitoring of a CAN network. eSys-IDC4E1 possesses an own logic for detecting error frames and counting them up in a specific internal memory area. Thus is used for finding intermittent errors like the falsified messages of a CAN participant.

Standardized SAE J2534 API

The Sontheim pass-thru API is supplied as a standard interface with eSys-IDC4E1. Thus, the module can be used for applications based on J2534. Further higher level protocols can be easily implemented on demand.

Software architecture

The software architecture of the CAN module consists of a host device structure in which a x86 PC-system as a hosts use the module as a device for access to the CAN bus. For communication between host and device Ethernet is used. The communication takes place via IP and a proprietary, on UDP based communication protocol. For identification (Discover) of the CAN interfaces over

CPU	Freescale PowerPC, 400 MHz
RAM	32 MB (optionally up to 128 MB)
Memory	16 MB (optionally up to 128 MB)
CAN interface	$4\times$ CAN interface galv. isolated, according to ISO 11898 Standard, 2.0 A and 2.0 B
Baud rates	50 Kbit/s up to 1 Mbit/s (incl. 800 Kbit/s)
CAN termination resistance measurement	Measurement of the terminating resistor of the CAN bus of the machine; measurement takes place with active bus $\frac{1}{2} \left(\frac{1}{2} \right) = \frac{1}{2} \left(\frac{1}{2} \right) \left(\frac{1}{2} $
CAN diagnostic	Error frame detection
CAN connections	4× D-Sub9
LAN	100 Mbit LAN, RJ45 connection
LEDs	LAN Status LED, green and yellow at RJ45 connection
Others	Can also be used as CAN-to-CAN bridge
CE-Sign	EN 61000-6-2 electromagnetic compatibility (EMC) Interference immunity (10V/m) EN 61000-6-4 electromagnetic compatibility (EMC) Interference emission EN 61000-4-2 immunity to static discharge (ESD) EN 61000-4-3 immunity to radio-frequency electromagnetic fields EN 61000-4-4 immunity against fast transient electrical disturbances EN 61000-4-5 interference immunity against surge voltages EN 61000-4-6 immunity to conducted disturbances induced by high-frequency fields
Dimensions (l×w×h)	approx. 121 mm × 151 mm × 48 mm – without connection
Housing	Aluminium housing, Protection class IP30
Storage temperature	−20°C up to +70°C
Operating temperature	0°C up to +60°C
Supply	24 V ±10 % / max. 1 A

Pin assignment

CAN D-Sub9



2 CAN low 3 CAN GND 7 CAN high

LAN-RJ45





CAN resistance measurement



1 120Ω CAN1 On/Off 2 120Ω CAN2 On/Off 3 120Ω CAN3 On/Off 4 120Ω CAN4 On/Off

Phoenix connection



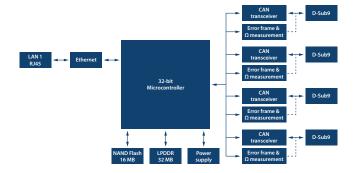
1 24 V 2 0 V 3 PE

LAN, the process according to ISO 13400 is used. The firmware of the CAN module is composed of a main thread, which handles the CAN communication and is also able to handle the transport layer communication protocols (e.g. J1939-21/J1939-81, ISO 15765), and a diagnostic thread for a self- and CAN diagnostic. All non-related services to the direct communication of the CAN module, such as the configuration of the bridging or CAN diagnostics are handled over the so-called "toolbox" protocol. The order of the received message at the host interface is the same order as on the physical bus, regardless whether the message was sent or received. Thus, an extremely high-performant communication is guaranteed at low latency.

Order information

1

Block diagram









COMfalcon®

COMfalcon® is a powerful CAN interface with WLAN/ LAN interface and various equipment options. Use it for monitoring, flashing or analyzing CAN networks and handling layer-7 protocols like CANopen or SAE J1939. It is a very flexible and easy to use tool for the detection of CAN data and monitoring of entire networks.

Key Features



4× independent CAN channels



WLAN interface











K-Line



Protocolhandling



Optional with data logging, scripting, CAN voltage level oscilloscope functionality



Optional with integrated SD card



Compact housing with protection class IP65

Housing and status indicators

The device has a fairly rugged housing built of aluminium with IP65 protection. Thanks to the compact design and high shock resistance, COMfalcon® can be used for various automation applications. Two 14-segment displays and nine LEDs are always showing the current status/error code of the device.

Interfaces

The COMfalcon® has four independent CAN channels and is based on the CAN interface CIN with a Freescale PowerPC architecture. WLAN/LAN (infrastructure mode) is used to connect to a diagnostic laptop/PC. In addition to the CAN interfaces a various of other interfaces such as RS232, RS422, RS485 or K-Line are available for diagnostic purposes.

Error frame detection

This feature allows surveillance and monitoring of a CAN network. The COMfalcon® possesses an own logic for detecting error frames and counting them up in a specific internal memory area. That is used for finding intermittent errors like falsified messages of a CAN participant.

CPU	Freescale PowerPC
RAM	64 MB
Memory	16 MB (for data logging optionally up to 128 MB)
CAN interface	4× CAN interface acc. to ISO 11898
Baud rates	50 Kbit/s up to 1 Mbit/s
CAN termination resistance measurement	Terminating resistor of the vehicle CAN network with active bus
CAN Port	2×7-pole M16 port (like Sontheim CANUSB-2)
RS232 interface	D-Sub9 Plug A
Serial multiplex interface	D-Sub9 Plug A; 5 different serial interfaces, changeable via software
K-/L-Line interface	K-/L-Line (acc. to ISO 9141-2, ISO 14230-4), Baud rate up to 56 kBaud/s
RS485 interface	EIA/TIA-485 compatible Baud rate up to 10 Mbit/s no integrated termination resistor
RS422 interface	ANSI/TIA/EIA-422 compatible Baud rate up to 10 Mbit/s no integrated termination resistor
LAN	M12 4-pin female connector 100 Mbit/s LAN, D-codiert
WLAN	1× acc. to IEEE 802.11g, up to 54 Mbit/s
14-segment display	Boot information, K-line mode, RS-mode, measurement, error codes
LEDs	Power LED (green) LAN status LED (green and yellow) WLAN status LED (green and yellow) 4× CAN status LED (green and yellow) 2× RS status LED (green and yellow)
Dimensions (l×w×h)	110 mm × 150 mm × 35 mm
Housing	Aluminium, protection class IP65
Storage temperature	−40°C up to +85°C
Operating temperature	−20°C up to +60°C
Supply	a.) 6 up to 32 V DC with load-dump protection b.) via USB V = 5 V, IMAX < 500 mA (with Mini-B- USB connector)

Pin assignment

RS1









1	N	C
2	R	S232 RX
3	R:	S232 TX
4	N	C
5	G	ND
6	N	C
7	N	C
8	re	served
9	re	served

CAN 1/2



1	CAN2 low
2	CAN2 high
3	NC
4	CAN1 low
5	CAN1 high
6	Ubat
7	CAN GND

CAN 3/4



1	CAN4 low
2	CAN4 high
3	NC
4	CAN3 low
5	CAN3 high
6	Ubat
7	CAN GND

LAN



1	TX+	
2	RX+	
3	TX-	
4	RX—	

Order information

V930232000 COMfalcon®





ID-based level measurement – resistance measurement/current measurement

This feature allows to read the CAN level even IO-related and to measure active and passive termination resistors, for example for various diagnostics on a machine. This is especially important if the network may lose data caused for example by short circuits.

The Sontheim Modular Diagnostic Tool Chain

You can easily create your individual and professional diagnostic solution for automation applications with the help of the Sontheim interfaces and diagnostic software. Some use cases by linking hardware and software are:

- · CAN data visualization, monitoring and processing
- Parameterization and control of whole CAN networks
- Machine diagnostics
- Flash processes of electronic control units (ECUs)



COMfalcon® plus

COMfalcon® plus is a powerful CAN Interface with WLAN/LAN and optional Bluetooth communication and various equipment options. Use it for monitoring, flashing or analyzing CAN networks and handling layer-7 protocols like CANopen or SAE J1939. Profit also from a Linux operating system and LUA scripting.

Key Features



4× independent CAN channels



WLAN interface



Bluetooth optional



RS232



K-Line



Protocolhandling



Optional with data logging, scripting, CAN voltage level oscilloscope functionality



Optional with integrated SD card



Compact housing with protection class IP65

Interfaces

The COMfalcon® plus has four independent CAN channels and a Freescale PowerPC architecture. WLAN/LAN and optional Bluetooth is used to connect to a diagnostic device. In addition to the CAN interfaces a various of other interfaces such as RS232 or K-Line are available for diagnostic purposes.

Housing and status indicators

The device has a fairly rugged housing built of aluminium with IP65 protection and a easy to use trigger button for logging data. Thanks to the compact design and high shock resistance, COMfalcon® plus can be used in various fields of the automation industry. Two 14-segment displays and nine LEDs are always showing the current status/error code of the device.

LUA Scripting

Own embedded applications are running directly on the COMfalcon® plus in LUA without the need of a third device. Several scripts can be run in parallel. Among other things, it's possible to create and implement own information, such as flash routines, ECU descriptions and more, and thus, for example, access to the CAN or file system. The embedded applications are portable and reusable for future Sontheim VCI generations.

CPU	Freescale PowerPC
RAM	64 MB
Memory	4 GB (up to 32 GB)
CAN interface	4× CAN interface acc. to ISO 11898
Baud rates	50 Kbit/s up to 1 Mbit/s
CAN termination resistance measurement	Terminating resistor of the vehicle CAN network with active bus
CAN Port	2×7-pole M16 port (like Sontheim CANUSB)
RS232, K-/L-Line interface	M12 5-Pin female connector
LAN	M12 4-pin female connector 10/100 Mbit LAN
WLAN	1× acc. IEEE 802.11b,g,n,d,e,i up to 65 Mbit/s
Bluetooth (optional)	2.1+EDR, Power Class 1.5, BLE 4.0 and ANT
USB	Type mini-B
14-segment display	Boot information, K-line mode, RS-mode, measurement, error codes
LEDs	LAN status LED (green and yellow) WLAN/Bluetooth status LED (green and yellow) 4× CAN status LED (green and yellow) RS232, K-/L-Line status LED (green and yellow)
Dimensions (l×w×h)	110 mm × 150 mm × 35 mm
Housing	Aluminium, protection class IP65
Storage temperature	−40°C up to +85°C
Operating temperature	-40°C up to +60°C
Supply	via CAN 12 V – 24 V

Pin assignment

CAN 1/2



1	CAN2 low
2	CAN2 high
3	CAN GND
4	CAN1 low
5	CAN1 high
6	Vbat
7	oV

CAN 3/4



1	CAN4 low
2	CAN4 high
3	CAN GND
4	CAN3 low
5	CAN3 high
6	Vbat
7	oV

RS232 / K-/L-Line



1	RS232_RX
2	RS232_TX
3	K_Line
4	L_Line
5	GND

USB



1	VCC
2	USB_D-
3	USB_D+
4	USB_ID
5	GND

LAN (green)







Error frame detection

This feature allows surveillance and monitoring of a CAN network. The COMfalcon® plus possesses an own logic for detecting error frames and counting them up in a specific internal memory area. That is used for finding intermittent errors like falsified messages of a CAN participant.

ID-based level measurement – resistance measurement/current measurement

This feature allows to read the CAN level even IO-related and to measure active and passive termination resistors, for example for various diagnostics on a machine. This is especially important if the network may lose data caused for example by short circuits.

The Sontheim Modular Diagnostic Tool Chain

You can easily create your individual and professional diagnostic solution for automation applications with the help of the Sontheim interfaces and diagnostic software. Some use cases by linking hardware and software are:

- · CAN data visualization, monitoring and processing
- Parameterization and control of whole CAN networks
- Machine diagnostics
- Flash processes of electronic control units (ECUs)

Order information

V930232400

COMfalcon® plus



CANfox®

CANfox® is a Sontheim fieldbus-to-USB adapter.
Besides its CAN interface it contains a RS232 channel for a maximum of flexibility. The device can be used for monitoring of CAN networks, setting parameters of machines etc.

Key Features



1× galv. isolated CAN interface acc. to ISO 11898



1× RS232



Connection via USB 2.0



Free configuration of baud rate including 800 Kbit/s



Powerful 32-bit microcontroller



CODESYS Gateway-driver available



Multi-Thread API for own applications



Driver for Windows 2000 up to Windows 10 with 32- and 64-bit

Housing and interfaces

It is housed in a compact plastic case and offers a CAN channel and a RS232 channel. CAN is implemented via a D-Sub9 connector according to CiA standard. Its USB 2.0 interface enables the CANfox® to be used at any laptop, embedded PC or desktop PC. Once you have installed the driver you will benefit from hot plug and play which is a connection of device to PC without restart. Consequently, CANfox® offers all necessary interfaces located in a tiny case for mobile or stationary use.

More performance, less costs

It is a powerful device within the Sontheim interface group with its 32-bit microcontroller for data-handling. However, the CANfox® is meant to be a flexible and very inexpensive tool. Thus, you can configure the baudrate via software and adapt it to your processes.

CPU	32-bit microcontroller
CAN	1x CAN interface acc. to ISO 11898, via D-Sub9
RS232	1× RS232 interface, via D-Sub9
USB	1× Standard USB Typ A, 75 cm cable length
Baud rates	50 Kbit/s up to 1 Mbit/s, free configuration
Max. Data transfer	1 Mbit/s at 90% Bus load
LEDs	3×3 mm LED
Housing	compact plastic
Operating temperature	−20°C up to +60°C
Storage temperature	−40 °C up to +85 °C
Rel. Humidity	20% – 90% non-condensing
Power supply	via USB interface
CANAPI (=Windows DLL)	Windows 2000, XP, Vista, 7, 8; 32-bit. Windows 98 on request

Pin assignment

1 2 3 4	VCC (VBUS) — Data + Data GND
7	UND

CAN

USB

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RS232





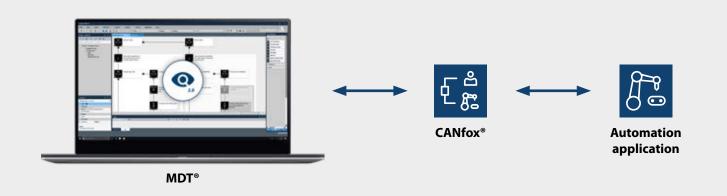
Comprehensive software support

Of course, CANfox® is supported by all Sontheim tools like CANexplorer 4 for CAN bus diagnostics or MDT® for machine applications like diagnostics or End-of-Line processes. With the help of the included software interface (API), users can also run their own software. There is also a CODESYS support implemented in order to use the device for PLC and motion control tasks. Use it as a programming gateway for CODESYS-based PLCs or for downloading programms directly out of a CODESYS programming environment.

The Sontheim Modular Diagnostic Tool Chain

You can easily create your individual and professional diagnostic solution for automation applications with the help of the Sontheim interfaces and diagnostic software. Some use cases by linking hardware and software are:

- · CAN data visualization, monitoring and processing
- Parameterization and control of whole CAN networks
- · Machine diagnostics
- Flash processes of electronic control units (ECUs)



Order information

V930322000 CANfox®



CANUSB

This is a top seller among the Sontheim interface family. It facilitates a quick and sturdy connection between PC or notebook and CAN bus. CANUSB is highly flexible, user-friendly and market-proven. Thousands of units are already in the field, used for monitoring of CAN networks, setting parameters of machines etc.

Key Features



Shock-resistant aluminium extrusion housing



1 or 2 galv. isolated CAN channels with 1 Mbit/s transfer capacity at 90 % bus load



Hot plug and play ensures fast and convenient commissioning



MT-API enables access to CAN bus for own applications



Optional variant with error frame detection



Ideal for use with a PC or notebook

Housing

The device has a fairly rugged housing built of aluminium. Its compact design and resistivity against shock make it very popular in many areas of the automation industry.

CAN channels

There are either 1 or 2 galvanically isolated CAN channels available which comply with ISO 11898-2. The transfer rate ranges up to 1 Mbit/s at 90% bus load.

Flexible data processing

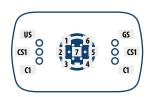
Its USB 2.0 interface enables the CANUSB to be used at any laptop, embedded PC or desktop PC. Once you have installed the driver you will benefit from hot plug and play which is a connection of device to PC without restart.

Microcontroller and firmware update

The Motorola STAR12 and the Philips PDIUSBD12 guarantee a quick data processing. Both CAN 2.0 A and CAN 2.0 B are supported. CANUSB is suited for numerous operating systems like Windows XP, XP embedded, Vista and 7. All firmware updates can be loaded via USB.

CPU CAN	Motorola Star12, 16-bit
CPU USB	Philips PDIUSB12
CAN	1× CAN interface acc. to ISO 11898-2, galv. isolated (optional 2× CAN)
USB	1× USB 2.0
CAN connection	1×7-pin round plug
USB connection	1× standard USB connector type A
Cable CAN	optional 2 m CANUSB cable
Cable USB	1 m Standard USB
Max. data transfer	1 Mbit/s at 90 % bus load
Error frame detection	optional
Analog level measurement	integrated
LEDs	2× triple 3 mm LED angled
Dimensions (l×w×h)	100 mm × 57 mm × 32 mm
Weight	166 g
Housing	Solid aluminium
Operating temperature	0 °C up to +70 °C
Storage temperature	−20°C up to +85°C
Rel. Humidity	20 % – 90 % non-condensing
Power consumption	max. 350 mA at 5 V
Power supply	via USB interface

Pin assignment





CAN

US	USB Status
CS1	CAN Status 1
C1	CAN 1 receive / transmit action
GS	Device status
CS2	CAN Status 2
C2	CAN 2 receive / transmit action
1	CAN2 low
2	CAN2 high
3	=
4	CAN1 low
5	CAN1 high
6	=
7	CAN GND



1	VCC (VBUS)
2	— Data
3	+ Data
4	GND

Order information

V930204000	CANUSB, 2× CAN, Errorframe, level measurement
V930205000	CANUSB, 2× CAN, Errorframe
V930206000	CANUSB, 2× CAN
V930207000	CANUSB, 1× CAN, Errorframe, level measurement
V930208000	CANUSB, 1× CAN, Errorframe
V930209000	CANUSB, 1× CAN
V930220000	CANUSB-cable, 2 m, 120 Ohm
V930220100	CANUSB-cable, 2 m, (2× D-Sub9 male)

Error frame detection

This feature allows surveillance and monitoring of a CAN network. The CANUSB possesses an own logic for detecting error frames and counting them up in a specific internal memory area. That is used for finding intermittent errors like falsified messages of a CAN participant.

Level measurement

This feature is designed for an analog measurement of CAN levels. It is used for doing diagnostics at vehicles of all kinds or machines. It is especially important when data is lost from the network, which can be caused by short circuits, for example.

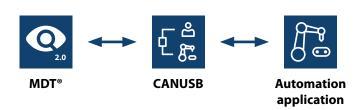
Programming interface

The CANapi provides all functions for programming own applications. It supports all Sontheim interfaces and several third-party devices which is why we enclose our SiECA132 MT-CANapi with four simultaneous handles at every interface dongle.

The Sontheim Modular Diagnostic Tool Chain

You can easily create your individual and professional diagnostic solution for automation applications with the help of the Sontheim interfaces and diagnostic software. Some use cases by linking hardware and software are:

- CAN data visualization, monitoring and processing
- Parameterization and control of whole CAN networks
- Machine diagnostics
- Flash processes of electronic control units (ECUs)





PowerCAN-PCI

PowerCAN-PCI V2 is a highly advanced and ultra-fast CAN controller card for the connection of PCs with PCI-slot to the CAN bus. It is able to handle the full control, regulation and parametrisation of small to complex CAN networks.

Key Features



PC assumes the function of a CANopen manager



Control of other CANopen devices, e.g. motor controls



Transmission performance of 1 Mbit/s at 90% bus load



Freescale Coldfire with 32 MHz clock frequency



2× galvanically isolated CAN channels



Equipment with high or low speed interface



LEDs for bus status display on the front bracket

Compatibility

The device is a PCI-card with two galvanically isolated CAN interfaces according to ISO 11898. Being fully compatible to PCI-specification 2.2, it can be used with any PC-system that has an unoccupied PCI-slot. Both active CAN controllers offer 15 message objects each and comply with FullCAN.

CPU

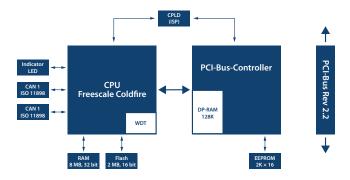
The Coldfire from Freescale is used as a powerful micro-controller. The controller is operated in 16-bit demultiplexed mode, which guarantees an optimal connection to the PCI controller. The implemented bootstrap loader makes it easy to load the firmware. Two "on-chip" CAN controllers realize the CAN connection in 2.0 B active mode.

Memory

Even complex fieldbus-controlling tasks can easily be handled with 8 MB RAM and 2 MB flash memory. There is no need for an external programming power supply, the flash memory is supplied with 5 V for writing and deleting. The flash also contains the firmware which can be updated via bootstrap-loader.

CPU	Freescale Coldfire		
RAM	8 MB		
Memory	2 MB		
CAN	2× CAN interface acc. to ISO 11898, galv. isolated		
CAN controller	2× FullCAN according to CiA (DIN41652)		
CAN transceiver	Philips 82C251		
CAN protocol	2.0 A and 2.0 B		
CAN connectors	2× D-Sub9		
Bus system	PCI		
PCI controller	acc. to PCI 2.2 specification 16k Dual-Port-RAM		
LED	4× LED (green)		
Dimensions (l×w×h)	164 mm × 102 mm × 13 mm		
Operating temperature	0°C up to +60°C		
Storage temperature	−20°C up to +75°C		
Rel. Humidity	20 % – 90 % non-condensing		
Power supply	5 V		
Power consumption	500 mA		
CANopen driver	for Windows NT		
Layer 2 driver	for Windows 98, ME, NT, 2000, XP, Vista, 7; 32-and 64-bit		

Blockschaltbild



Pin assignment



CAN

- 2 CAN low 3 CAN Ground
- 7 CAN high

Order information

V930154000 PowerCAN-PC

CAN interface

Two galvanically isolated CAN channels with a transfer rate of up to 1 Mbit/s provide the necessary controlling power. In addition to that there are two active 2.0 B CAN controller implemented that allow a mixed mode with 11-Bit and 29-Bit identifiers. The CAN interface complies with ISO 11898 standard as well as DS 301 and 401.

Error frame detection

This feature allows surveillance and monitoring of a CAN network. The PowerCAN card possesses an own logic for detecting error frames and counting them up in a specific internal memory area. That is used for finding intermittent errors like falsified messages of a CAN participant.



CIN

CIN is a board variant of the Sontheim CAN adapters with numerous interfaces for communication. Its extended temperature range and a number of diagnostic functions make it a perfect embedded module for industrial signal applications.

Key Features



Freescale microcontroller



Wide range of interfaces



Can be used as a board solution or as a communication centre in the Diag-Box



Internal flash and RAM memory



Also suitable for harsh environments due to increased temperature range



Extensive software support

Interfaces

There are four CAN interfaces next to two single-wire CAN, eight digital inputs and eight digital outputs. Moreover, CIN uses ethernet and I²C for controlling peripheral components. It is possible to have it assembled either as a piggyback board onto another PCB or in the Diag-Box as a high-performance communication node. The ethernet channel is also used for building up a gateway function for CAN-to-Ethernet.

Error frame detection

Similar to a CANUSB, CIN is equipped with error frame detection. This feature allows surveillance and monitoring of a CAN network. It has an own logic for detecting error frames and counting them up in a specific internal memory area. That is used for finding intermittent errors like falsified messages of a CAN participant.

Level measurement

This feature is designed for an analog measurement of CAN levels. It is used for doing diagnostics at vehicles of all kinds or machines. Erratic level indicate for example short circuits. They are often responsible for data loss.

CPU	Freescale MPC 512x
RAM	32 MB, optionally 64 and 128 MB available
Memory	16 MB
Ethernet/PHY	10/100 Mbit/s
CAN interfaces	$4\times$ CAN transceivers, first transceiver with wake-on-CAN function Bus termination: $120~\Omega$, optionally mounted on circuit board Diagnostics: ErrorFrame detection on separate FPGA for all channels Diagnostics: Analog level measurement with simultaneous measurement of CAN high and CAN low CAN channels are not galvanically isolated
Digital input	8×, power supply 3.3 V
Digital output	8×, power supply 3.3 V, 10 mA
Single wire CAN	2x
I ² C	1x
Assembly	Customized circuit board solution or Diag-Box
Software support	CANexplorer 4, MDT®, ODX-Editor, SiECA132 MT-API and others on request
Operating temperature	−20 °C up to +85 °C
Storage temperature	−40 °C up to +85 °C
Power supply	+UBat (12 V or 24 V), +3.3 V, 5 V
More	Can also be used as CAN-to-Ethernet bridge/gateway

Order information

V930230120 CIN MPC5123 Error frame, level measurement



IoT Device Manager

Cloud-based platform for managing your devices in the field.

Key Features



Management of all telematics units



Drag and drop functionality



Managing updates over-the-air



Simple configuration of all devices



Fast data consumption analysis



Live data monitoring

The IoT Device Manager is a cloud-based tool for the simple and clear management of your telematics units in the field. You can group and structure your devices by drag and drop and manage software packages for wireless over-the-air updates.

Collect live data during vehicle operation or flash software wirelessly:

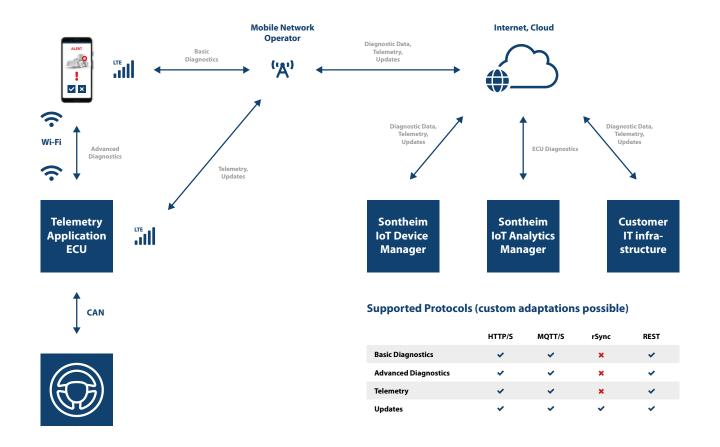
- Mobile networks (2G/LTE)
- WLAN

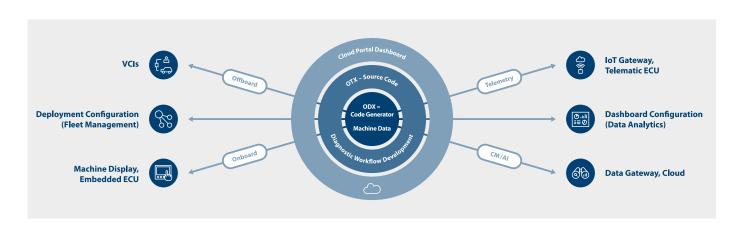
Store telemetry data for further analysis and support the following functions:

- QA Statistics
- Usage statistics
- · Planning of service intervals
- · vehicle lifecycle support

Store telemetry data and check information such as:

- SIM card number (IMSI)
- · Serial number of the LTE device
- Last connection to the server
- · Signal Quality
- Network Bandwidth
- · Device configuration





The IoT Device Manager can be hosted on a server on the Sontheim side or seamlessly integrated into an existing customer infrastructure. Secure data transfer is ensured thanks to SSL/TLS certification and can even be extended according to individual customer requirements. The IoT Device Manager can be branded OEM-specific. This allows the user to create different user levels, for viewing with different rights or for easy integration of sub supplier views.

Order information

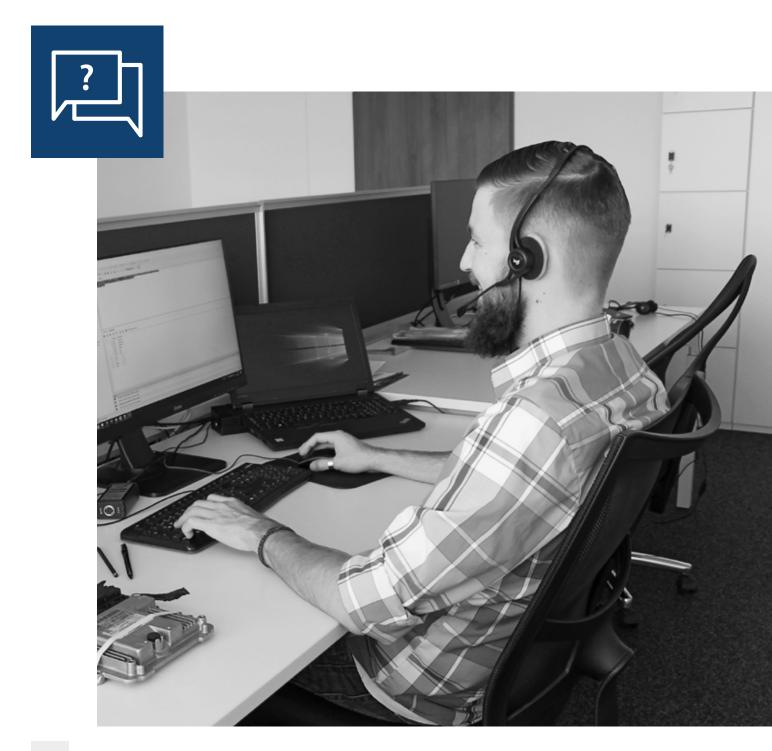
V940871100 IoT De

IoT Device Manager

Do you have Questions?

Please feel free to contact us. If you have any questions, suggestions or requests regarding our products and the company, we will be happy to help you.

You can reach us at info@s-i-e.de







Mobile Automation



Industrial Automation



Diagnostics



Connectivity

We are looking forward to your enquiry!

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